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SPACE-CHARGE-FLOW THEORY AND ELECTRODE DESIGN

FOR ELECTROSTATIC ROCKET ENGINES

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#### SUMMARY

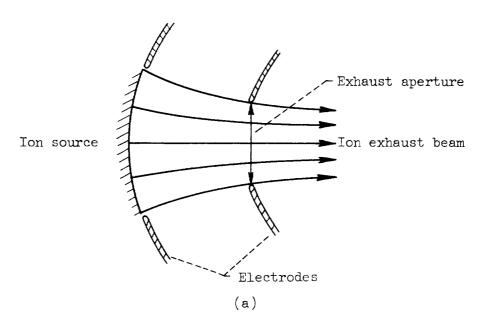
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The basic theory of space-charge flow is described, and three general methods of solution are discussed. Specific space-charge-flow geometries are described in detail; these include flow between coaxial cylinders, concentric spheres, coaxial cones, hyperbolic flow, flow between inclined planes, and circular flow. Since all the solutions discussed are for space-charge-limited flow, a discussion of partial space-charge flow is presented. The Pierce method of electrode design is described, and some practical limitations of this method are discussed. Electrode shapes for various space-charge flows are shown.

#### INTRODUCTION

The performance and design requirements of electrostatic rocket engines have brought a new emphasis to the theory of space-charge flow. Considerable reductions in engine size and substantial improvement in engine efficiency may be gained by the use of ion and charged-particle accelerators operating with current densities at or near the spacecharge limit. Such high current densities bring about definite spacecharge effects, so that Poisson's equation must be used to describe the potential distribution in the engine accelerator. In addition to the requirement of high current density, the electrostatic rocket engine must be capable of operating for very long times, of the order of years for interplanetary space missions. Such long-duration operation requires near-perfect "ion optics" to keep electrode sputtering erosion to reasonable limits. Since the ions, or charged particles, are accelerated to kinetic energies in the range from a few thousand to hundreds of thousands of electron volts, each ion striking an electrode may sputter away several electrode atoms. For these reasons, some estimates of the degree of perfection of ion optics place an upper limit of ion impingement of less than 0.01 to 0.1 percent of the total ion beam to keep erosion to a reasonable level.

The space-charge-flow problem in electrostatic rocket engines is characterized by the necessity for the ions, or charged particles, to leave the engine permanently through an open exhaust aperture, as shown in sketch (a):



Since the ion source is at a potential considerably higher (or lower, for negative ions) than the potential of free space, the equipotential lines in the accelerator will tend to bow, or bulge, out of the exhaust aperture. This aperture effect not only reduces the current carrying capacity of the accelerator, but also introduces another complicating boundary condition on the space-charge-flow equations.

The complexities of the space-charge flow in electrostatic rocket engines indicate that complete analytical design of space-charge-flow accelerators will be very difficult. For this reason, recourse has been made to analog or empirical methods (i.e., experimental "cut-and-try"). Not only are these methods inadequate for extrapolation or scaling of engine designs, but in addition they do not offer sufficient basic understanding of space-charge flow to allow positive prediction and evaluation of the effects of configuration changes in design optimization studies.

It is evident that a convenient, universal method for the analytic solution of the space-charge-flow problem would be of great value in the design of electrostatic rocket engines. The survey of existing literature on space-charge flow reported herein has yielded no completely universal analytic method, but some progress has been made in that direction.

The first section of this report is devoted to a discussion of the three methods of solution that have been used to date for space-charge-flow problems. The remainder of the section on space-charge-flow theory is a compilation of analytic solutions for specific space-charge-flow geometries found in the literature and also includes a calculation of the flow between coaxial cones that was not previously available.

Since the analytic solutions to space-charge flow usually assume that the flow fills all space, it is necessary to take a segment of this flow and to provide electrodes external to the ion beam to force the flow to conform to the theoretical pattern. The second section of this report is devoted to the problem of electrode design. The method of Pierce is described and is applied to a number of space-charge-flow geometries to obtain electrode shapes. Some of these shapes are accurately recomputed using techniques found in the literature, and others appear not to have been computed previously. Some practical limitations to the application of space-charge flow theory and the Pierce method of electrode design are discussed.

The parameters of the various space-charge flows examined in this report may be used to determine the theoretical performance of electrostatic rocket engines. An analysis is made in reference 1 in which the various space-charge flows are compared in terms of relative engine performance.

The work described in this report was carried out as part of the electrostatic propulsion research program of the NASA Lewis Research Center.

#### SPACE-CHARGE-FLOW THEORY

In the study of the performance of ion engines the analysis of space-charge flow is very important. Since the early studies of Child (1911, ref. 2) and Langmuir (1913, ref. 3), who solved the problem of space-charge-limited flow between parallel plates more than half a century ago, there have appeared extensive publications on space-charge effects in certain new geometries. Most of the early analyses (refs. 2 to 5) have been concerned with one-dimensional cases, and it has been only in recent years that two- and three-dimensional cases were solved or solutions were suggested (refs. 6 to 13).

In most ion engines, ions move as a very nearly continuous fluid in an electrostatic field in which the magnetic force is negligible. The flow of ions is assumed to form a system of curves (streamlines) filling a portion of space such that the velocity is a single-valued function of position.

The fundamental differential equations governing steady-state space-charge flow are:

Poisson's equation:

$$\nabla^2 \Phi = \frac{\rho}{\epsilon_0} \tag{1}$$

Equation of motion:

$$\overrightarrow{mv} = q\nabla \Phi \tag{2}$$

Conservation of charge:

$$\nabla \cdot \vec{j} = 0 \tag{3}$$

(Note that  $\Phi = \phi_O - \phi_\bullet$ )

It is mathematically convenient to assume that the flow is space-charge limited. In this case the velocity and electric field will both be zero on the emitting surface. Under these conditions it can readily be shown (ref. 9) that the flow will be irrotational; that is,

$$\nabla \times \vec{v} = 0 \tag{4}$$

In this case, the velocity can be expressed as the gradient of a scalar action function:

$$\vec{\mathbf{v}} = \nabla \mathbf{W} \tag{5}$$

Combining equation (5) with the vector identity  $\vec{v} = (\vec{v} \cdot \nabla)\vec{v}$  yields

$$\vec{v} = (\nabla W \cdot \nabla) \nabla W \tag{6}$$

Application of equation (4) to the identity

$$(\forall W \cdot \nabla) \forall W = \frac{1}{2} \forall (\forall W)^2 - \forall W \times (\forall \times \forall W)$$

gives

$$\dot{\vec{v}} = \frac{1}{2} \nabla (\nabla W)^2 \tag{7}$$

Substitution for  $\dot{\vec{v}}$  from equation (2) yields

$$\nabla(\nabla W)^2 = \left(\frac{2q}{m}\right)\nabla\Phi \tag{8}$$

Hence,

$$\left(\nabla W\right)^{2} = \left(\frac{2q}{m}\right)\Phi \tag{9}$$

where the constant of integration is included by letting  $\Phi$  =  $\phi_{\text{O}}$  -  $\phi_{\text{O}}$ 

The five equations used to formulate space-charge-flow problems are: Hamilton-Jacobi equation:

$$\left(\nabla W\right)^{2} = \left(\frac{2q}{m}\right)\Phi \tag{9}$$

Poisson's equation:

$$\nabla^2 \Phi = \frac{\rho}{\epsilon_0} \tag{1}$$

Total ion energy:

$$\frac{1}{2} mv^2 - q\Phi = 0 \tag{10}$$

Conservation of charge:

$$\nabla \cdot \vec{j} = 0 \tag{3}$$

Vector current density:

$$\vec{j} = \vec{\rho V} \tag{11}$$

#### Analytical Methods

Historically the first analytical solutions of the space-charge-flow problem were for particular cases of rectilinear flow between specified equipotential surfaces. These are flow between infinite planes (refs. 2 and 3), flow between coaxial cylinders (refs. 3 and 4), and flow between concentric spheres (ref. 5). One of the first attempts at a general solution of the space-charge-flow equations was made by Spangenberg (ref. 6) following his formulation of the general equations in terms of the action

function. His multidimensional analysis yields a partial differential equation in terms of the action function, which is much too unwieldy for exact solution.

In 1949 Meltzer (ref. 7) introduced a unique approach to the solution of space-charge-flow problems. By his method the space-charge-flow parameters are expressed in terms of the acceleration and velocity. Meltzer shows that there are two conditions necessary for a space-charge solution to exist; namely,

$$\nabla \times \overset{:}{\mathbf{v}} = 0 \tag{12}$$

$$\nabla \cdot (\vec{\mathbf{v}} \nabla \cdot \dot{\vec{\mathbf{v}}}) = 0 \tag{13}$$

Using the relation  $\dot{\vec{v}} = (\vec{v} \cdot \nabla) \vec{v}$  to obtain the acceleration from a previously assumed velocity, v and  $\dot{v}$  are tested in equations (12) and (13). If they satisfy (12) and (13), they define a type of spacecharge flow whose parameters are as follows:

$$\rho = \left(\frac{m}{q}\right) \epsilon_{O}(\nabla \cdot \dot{\nabla}) \tag{14}$$

$$\nabla \Phi = \left(\frac{m}{q}\right)^{\frac{1}{2}} \tag{15}$$

$$\Phi = \left(\frac{m}{q}\right) \oint \dot{\vec{v}} \cdot d\vec{s}$$
 (16)

$$\vec{j} = \left(\frac{m}{q}\right) \epsilon_{\mathcal{O}} \vec{v} (\nabla \cdot \vec{v}) \tag{17}$$

This method leaves one big equation unanswered. How may a velocity function be found that will satisfy equations (12) and (13)? The search for an answer to this question led Meltzer (ref. 11) and later Rosenblatt (ref. 12) to develop the trajectory action function method, which is more readily applicable to space-charge-flow problems than any previous method.

In the action function method of Meltzer and Rosenblatt it is assumed that the flow of charged particles is laminar, and that an orthogonal curvilinear coordinate system

$$\xi(x,y,z) \tag{18a}$$

$$\eta(x,y,z) \tag{18b}$$

$$t(x,y,z) \tag{18c}$$

can be found such that the ion trajectories are completely described by variation of the parameters  $\eta$  and  $\zeta$  (i.e.,  $\eta$  = const. and  $\zeta$  = const. specify a particular trajectory). Then the orthogonal surfaces  $\xi$  = constant will be surfaces of constant action, and the Hamilton-Jacobi equation (9) becomes

$$\frac{1}{h_1^2} \left( \frac{dW}{d\xi} \right)^2 = \left( \frac{2q}{m} \right) \Phi \tag{19}$$

where  $h_{\hat{L}}$  is the scale factor corresponding to the coordinate  $\,\xi_{\star}\,$  Rosenblatt shows that if a function  $\,\Gamma\,$  is defined such that

$$\Gamma = h_1^2 \Phi \tag{20}$$

the general differential equation for space-charge flow can be written

$$\Gamma^{1/2} \left[ \frac{\partial}{\partial \xi} \left( C \frac{d\Gamma}{d\xi} \right) + B\Gamma \right] = K(\eta, \zeta)$$
 (21)

where

$$C = \frac{h_2 h_3}{h_1^5}$$
 (22)

$$B = \left(\frac{h_2 h_3}{h_1}\right) \sqrt{2} \left(\frac{1}{h_1^2}\right) \tag{23}$$

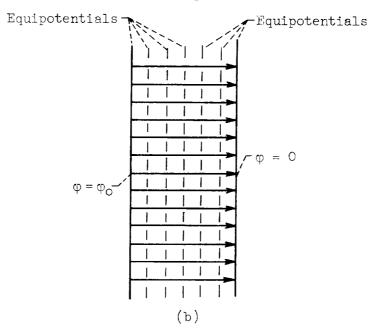
$$K(\eta, \zeta) = \frac{h_2 h_3}{\epsilon_0} j \sqrt{\frac{m}{2q}}$$
 (24)

The differential equations for several known space-charge-flow cases are derivable from equations (21), (22), (23), and (24). The variables  $\xi$ ,  $\eta$ , and  $\zeta$ , the scale factors, and equations (21) to (24) are tabulated for certain of these cases in table I. It is still necessary, however, to apply the classical techniques to obtain final solutions.

### Particular Solutions of Space-Charge Flow

It is of interest here to discuss particular solutions of the differential equations listed in table I and to express these solutions in nomographic form. In addition to these previously listed space-charge-flow solutions, there are two other known analytic space-charge flows included in the following sections.

Rectilinear flow between infinite plane electrodes. - Sketch (b) illustrates rectilinear flow between plane electrodes.



In 1911, Child (ref. 2) published the solution to this case. From his analysis he obtained what is now known as the Child-Langmuir space-charge law:

$$j = \frac{4}{9} \epsilon_0 \sqrt{\frac{2q}{m}} \frac{(\phi_0 - \phi)^{3/2}}{x^2}$$
 (25)

where  $\varphi_0$  is the potential at x=0. When the constants are written:

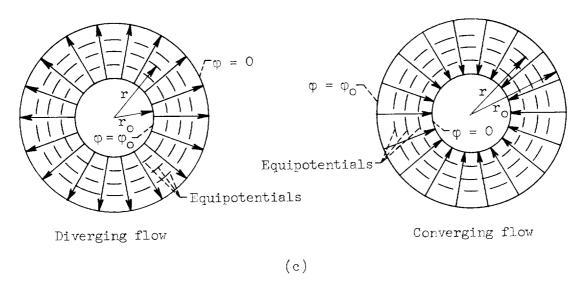
$$\frac{4}{9} \in \sqrt{\frac{2q}{m}} = 5.467 \times 10^{-8} \text{ A}^{-1/2}$$

where A is the molecular weight per ionic charge, equation (25) becomes

$$j = 5.467 \times 10^{-8} A^{-1/2} (\phi_0 - \phi)^{3/2} x^{-2}$$
 (26)

A nomogram relating j,  $(\phi_0 - \phi)$ , A, and x is shown in figure 1. The velocity v as shown in equation (10) is obtained for this and each subsequent case from the nomogram in figure 2.

Rectilinear flow between coaxial cylinders is shown in sketch (c).



In 1913 a paper by Langmuir (ref. 3) was published that contained an approximate solution for this type of flow. The current density and current per unit length may be written

$$j = 5.467 \times 10^{-8} A^{-1/2} (\phi_0 - \phi)^{3/2} r^{-2} \beta^{-2}$$
 (27)

$$\frac{J}{l} = 2\pi r j = 3.43 \times 10^{-7} A^{-1/2} (\phi_0 - \phi)^{3/2} (r\beta^2)^{-1}$$
 (28)

where  $\phi_0$  is the potential at  $r_0$  and  $\beta$  is a nondimensional function of r expressed as a power series in  $\ln(r/r_0)$ .

In 1923 an improved solution by Langmuir and Blodgett (ref. 4) was published. Two series representations for  $\beta$  were given. One of these most useful for electrode design is:

$$\beta = \left(\frac{r}{r_0}\right)^{-1/2} \left[ \left( \ln \frac{r}{r_0} \right) + 0.1 \left( \ln \frac{r}{r_0} \right)^2 + 0.0167 \left( \ln \frac{r}{r_0} \right)^3 + \dots \right]$$
 (29)

The Langmuir function  $\beta^2$  is plotted as a function of  $r/r_0$  in figure 3 and is tabulated in table II. Note that  $\beta^2$  for  $r/r_0 > 1$  is for divergent flow (from the inner to the outer cylinder), and  $\beta^2$  for  $r/r_0 < 1$  is for convergent flow. The numbers in table II were computed from equation (29) using all 14 coefficients given by Langmuir in reference 4. These numbers agree well with those shown by Langmuir. Nomograms relating J/l,  $(\phi_0 - \phi)$ , A, r,  $r/r_0$ , and v are shown in figures 2, 4, and 5.

Rectilinear flow between concentric spheres. - Sketch C also depicts rectilinear flow between concentric spheres. The solution for this case, due to Langmuir and Blodgett (ref. 5), was published in 1924. The current density and total current may be written

$$j = 5.467 \times 10^{-8} A^{-1/2} (\phi_0 - \phi)^{3/2} r^{-2} \alpha^{-2}$$
 (30)

$$J = 4\pi r^{2} j = 6.87 \times 10^{-7} A^{-1/2} (\phi_{0} - \phi)^{3/2} \alpha^{-2}$$
 (31)

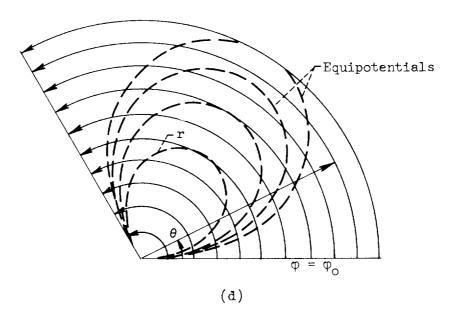
where  $\,\alpha\,$  is a nondimensional function of  $\,r\,$  expressed as the power series

$$\alpha = \left[ \left( \ln \frac{r}{r_0} \right) - 0.3 \left( \ln \frac{r}{r_0} \right)^2 + 0.075 \left( \ln \frac{r}{r_0} \right)^3 - 0.014 \left( \ln \frac{r}{r_0} \right)^4 + \dots \right]$$
(32)

The Langmuir function  $\alpha^2$  is plotted as a function of  $r/r_0$  in figure 6 and is tabulated in table III. As in the cylindrical flow case,  $\alpha^2$  for  $r/r_0 > 1$  corresponds to diverging flow and  $\alpha^2$  for  $r/r_0 < 1$  to converging flow. The numbers in table III were computed from equation (32) and agree well with Langmuir's data.

Nomograms relating J,  $(\phi_0 - \phi)$ , A,  $r/r_0$ , and v are shown in figures 2, 7, and 8.

Circular flow. - Circular flow is depicted in sketch (d).



The solution to this case is given by Meltzer in reference 11. The current density may be written

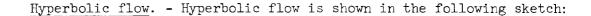
$$j = 1.23 \times 10^{-7} A^{-1/2} (\phi_0 - \phi)^{3/2} \left( r \sin \frac{3\theta}{2} \right)^{-2}$$
 (33)

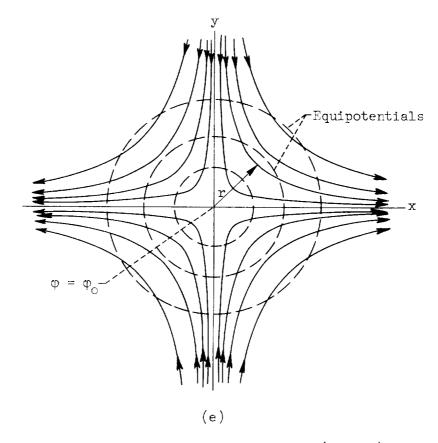
where  $\phi$  is the potential at  $(r,\theta)$  and j is the current density in the current sheet r. Figure 9 is a nomogram relating j,  $(\phi_0 - \phi)$ , A, r, and  $\theta$ . The velocity can be obtained from figure 2. This flow has several peculiarities that are not evident from equation (33). Since these are discussed in reference 11, they will only be mentioned here. First of all, the ions accelerate through an angle of  $60^\circ$  and then decelerate, reaching zero velocity at  $120^\circ$ . Since the equipotentials do not lie along a radial plane except at  $\theta = 0^\circ$  and  $\theta = 120^\circ$ , the velocity varies along any radial plane in the flow. Finally, along any radial plane the current density j is proportional to  $1/r^5$ . This poses a very difficult problem in ionizer design.

If a beam is considered that is bounded by an inner trajectory of radius a and an outer trajectory of radius b, the current per unit length may be written

$$\frac{J}{l} = 3.08 \times 10^{-8} A^{-1/2} \left(\frac{1}{a}\right) \left(1 - \frac{a^4}{b^4}\right) (\phi_0 - \phi)^{3/2} \left(\sin \frac{3\theta}{2}\right)^{-2}$$
 (34)

This equation is used in the electrode design section.





The solution to this case was obtained by Meltzer (ref. 7) and later by Rosenblatt (ref. 12). The space-charge-limited current density may be written:

$$j = 4.92 \times 10^{-7} A^{-1/2} (\phi_0 - \phi)^{3/2} r^{-2}$$
 (35)

where  $\varphi$  is the potential at radius r. This equation is expressed in terms of a nomogram in figure 10. It is interesting to note that J along any given trajectory is a function only of the radial component of the trajectory. If the bounding trajectory is defined by the equation  $y = (\lambda/x)$ , the current per unit length for one quadrant may be written

$$\frac{J}{l} = 4.92 \times 10^{-7} A^{-1/2} \lambda (\phi_0 - \phi)^{3/2} \left( x^2 + \frac{\lambda^2}{x^2} \right)^{-3/2}$$
 (36)

where Z is measured normal to the (x,y) plane.

Flow between two inclined planar electrodes. - The configuration of two inclined planar electrodes presents a very interesting problem of space-charge flow applicable to ion engine design.

Walker (ref. 9) solved this problem by first assuming negligible space charge. In this case the potential distribution between two inclined planar electrodes is known and can be written:

$$\Phi = \frac{\Phi_0}{\alpha} \theta \tag{37}$$

By substituting (37) into Hamilton-Jacobi equation (9) in polar coordinates, equation (9) then becomes

$$\left(\frac{\partial \mathbf{W}}{\partial \mathbf{r}}\right)^{2} + \left(\frac{1}{\mathbf{r}} \frac{\partial \mathbf{W}}{\partial \theta}\right)^{2} = \frac{2\mathbf{q}}{\mathbf{m}} \frac{\varphi_{0}}{\alpha} \theta \tag{38}$$

Because the right side of equation (38) is independent of r, so must be also the left side of (38). Therefore, Walker (ref. 9) sought a solution of the action function in the form

$$W = rz(\theta) \tag{39}$$

By substituting (39) into (38) the Hamilton-Jacobi equation becomes

$$z^{2} + z^{2} = \left(\frac{2q}{m} \frac{\varphi_{0}}{\alpha}\right) \theta \tag{40}$$

where  $z = \frac{\partial W}{\partial r}$  and  $z' = \frac{1}{r} \frac{\partial W}{\partial \theta}$ . Equation (40) was solved by Walker in the form of a power series.

The components of velocity are then given by

$$v_r = \frac{\partial W}{\partial r} = z$$

$$v_{\theta} = \frac{1}{r} \frac{\partial W}{\partial \theta} = z'$$

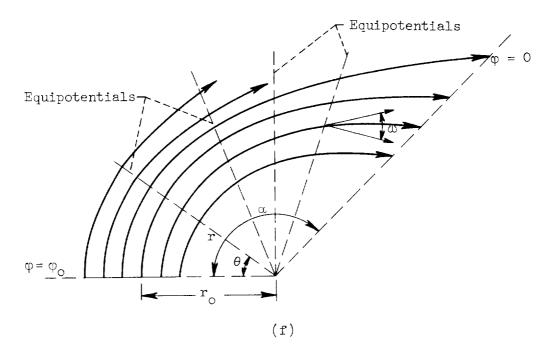
Hence,

$$\frac{\mathrm{d}\mathbf{r}}{\mathbf{r}} = \frac{\mathbf{z}}{\mathbf{z}^{\mathsf{r}}} \, \mathrm{d}\theta$$

and after integration the trajectory equation is obtained:

$$\frac{\mathbf{r}}{\mathbf{r}_{0}} = \exp\left(\int_{0}^{\theta} \frac{\mathbf{z}}{\mathbf{z}'} \, \mathrm{d}\theta\right) \tag{41}$$

where  $(r_0,0)$  is the initial point of a particular trajectory, and  $(r,\theta)$  are the coordinates of the remainder of that particular trajectory (sketch (f)).



The angle between the trajectory and the normal to equipotential is given by

$$\tan \omega = \frac{dr}{r \ d\theta} = \frac{z}{z'} \tag{42}$$

In the case of space-charge flow between two inclined planar electrodes, Walker assumed an action function in the form

$$W = rg(\theta) \tag{43}$$

By substituting (43) into Hamilton-Jacobi equation (9), equation (9) becomes

$$g^2 + g^{12} = \left(\frac{2q}{m}\right)\Phi \tag{44}$$

Now the left side of equation (44) is a function of  $\theta$  only; and, hence,  $\Phi$  must be a function of  $\theta$  only.

By expressing Poisson's equation (1) in polar coordinates, it follows that

$$\rho = \frac{\epsilon_0 \Phi''}{r^2} \tag{45}$$

The components of vector current density are

$$j_{\mathbf{r}} = \frac{\epsilon_0 \Phi'' g}{r^2}$$

and

$$j_{\theta} = \frac{\epsilon_{0}\Phi''g'}{r^{2}}$$

By substituting these components into the equation of conservation of charge (eq. (3))

$$\nabla \cdot \vec{j} = \frac{\partial j_r}{\partial r} + \frac{1}{r} j_r + \frac{1}{r} \frac{\partial j_{\theta}}{\partial \theta} = 0$$

Walker obtained

$$\frac{\mathrm{d}}{\mathrm{d}\theta} \left( \Phi'' \mathbf{g}' \right) - \Phi'' \mathbf{g} = 0 \tag{46}$$

By eliminating  $\Phi$  from equations (44) and (46) an ordinary fourth-order differential equation in g is obtained in the form

$$g'''' + g'' \left[ 4 \left( \frac{g'''}{g'} + 1 \right) + \frac{g''^2 - g^2}{g'^2} \right] - g = 0$$
 (47)

Any solution of this equation defines a possible motion. In a fashion similar to that in the space-charge-free case the trajectory equation is given by

$$\frac{r}{r_0} = \exp\left(\int_0^\theta \frac{g}{g'} d\theta\right) \tag{48}$$

and the angle between the trajectory and the normal to the equipotential is given by

$$\tan \omega = \frac{dr}{r \ d\theta} = \frac{g}{g!} \tag{49}$$

Ivey (ref. 10) made a detailed calculation of this problem and his results of equations (41), (42), (48), and (49) are presented in figures 11 and 12.

The space-charge-limited current density of the emitter as calculated in reference 10 is

$$j = \frac{4}{9} \epsilon_0 \left(\frac{2q}{m}\right)^{1/2} \frac{\Phi^{3/2}}{r_0^2} F(\alpha)$$
 (50)

where  $F(\alpha)$  could be defined as a perveance function depending on the magnitude of the angle  $\alpha$  shown in sketch (f). At any place in the flow the current density may be written

$$j = \frac{j_0(\theta)}{r/r_0}$$

Substitution into equation (50) yields

$$j = \frac{4}{9} \epsilon_0 \left(\frac{2q}{m}\right)^{1/2} \frac{\Phi^{3/2}}{r^2} \left[ \left(\frac{r}{r_0}\right) F(\theta) \right]$$
 (51)

where  $\phi$  is the potential difference between  $\theta=0$  and  $\theta$ , and the range of  $\theta$  is  $0 \le \theta \le \alpha$ . A nomogram of equation (51) is shown in figure 13 where  $\frac{4}{9} \epsilon_0 \sqrt{\frac{2q}{m}} = 5.467 \times 10^{-8} \text{ A}^{-1/2}$  for singly charged ions.

The normalized potential distribution for space-charge-limited flow as a function of normalized angle  $\theta/\alpha$  is shown in figure 14 for several values of  $\alpha$ . It is interesting to note that for  $\alpha=0$  the potential distribution is that for two parallel planes and, further, that the po-

tential distribution for  $\alpha < \pi/2$  is not greatly different from that

for  $\alpha = 0$ .

Flow between two coaxial right circular conical electrodes whose vertexes coincide. - In this configuration it is also assumed, as in the case of the flow between two inclined planar electrodes, that the end effects can be taken care of in all directions. Walker has outlined the

(52)

procedure for the solution of this problem for the space-charge flow (see sketch (g)). The authors of this paper assumed an action function in the form

$$\varphi = 0 \qquad \varphi = \varphi_0 \qquad \varphi = 0$$

$$\varphi = \varphi_0 \qquad \varphi = 0$$

Kino and Harker (ref. 13) in their analysis used a similar form of action function 
$$W = r^n \cdot s(\theta)$$
 and investigated cases for  $n < 1$ . Some of the cases investigated in their paper show beam trajectories that pass through potential minimums (accelerate-decelerate system). In the case of  $W = r \cdot s(\theta)$ , investigated herein, the beam trajectories are continuously accelerated (accelerate system).

(g)

By substituting (52) into Hamilton-Jacobi equation (9) this equation becomes

$$s^2 + s'^2 = \left(\frac{2q}{m}\right) \varphi \tag{53}$$

As in the case of the flow between two inclined planes, it was deduced that  $\phi$  has to be a function of  $\theta$  only.

By expressing Poisson's equation (1) in spherical polar coordinates, it follows that

$$\rho = \frac{\epsilon_0}{r^2} \left( \frac{\varphi'}{\tan \theta} + \varphi'' \right) \tag{54}$$

The components of the vector current density are

$$j_{r} = \frac{\epsilon_{0}^{s}}{r^{2}} \left( \frac{\varphi'}{\tan \theta} + \varphi'' \right)$$

$$j_{\theta} = \frac{\epsilon_{0}^{s'}}{r^{2}} \left( \frac{\varphi'}{\tan \theta} + \varphi'' \right)$$
(55)

and

The conservation of current equation (3) in spherical polar coordinates is

$$\nabla \cdot \overrightarrow{j} = \left(\frac{2j_r}{r} + \frac{\partial j_r}{\partial r} + \frac{j_\theta}{r \tan \theta} + \frac{1}{r} \frac{\partial j_\theta}{\partial \theta}\right) = 0$$
 (56)

Substituting equation (55) into (56) gives then the condition for which div j is zero, namely, when

cot 
$$\theta(2\phi''s' + \phi's'') + \phi'''s' + \phi''s'' - \phi's' = 0$$
 (57)

By eliminating  $\phi$  from equations (53) and (57) a fourth-order nonlinear ordinary differential equation in s is obtained in the form

$$s'''' = -\cot \theta \left[ 2(s''' + s') + 3\frac{s''}{s'}(s'' + s) \right] - \frac{2s''}{s'} \left[ 2s''' + \frac{s''(s'' + s)}{2s'} \right] + s\left(1 - \frac{s'''}{s'}\right) - 3s''$$
 (58)

Equation (58) was solved numerically for  $s(\theta)$  and  $s'(\theta)$ , which were then used for determination of ion trajectories.

The components of velocity are

$$v_r = \frac{\partial W}{\partial r} = s$$

and

$$v_{\theta} = \frac{1}{r} \frac{\partial \theta}{\partial \theta} = s'$$

and

$$\frac{d\mathbf{r}}{\mathbf{r}} = \frac{\mathbf{s}}{\mathbf{s}'} d\theta$$

and by integration

$$\frac{\mathbf{r}}{\mathbf{r}_{0}} = \exp\left(\int_{0}^{\theta} \frac{\mathbf{s}}{\mathbf{s}^{\mathsf{T}}} \, \mathrm{d}\theta\right) \tag{59}$$

The angle between the trajectories and the normals to the equipotentials is given by

$$\tan \gamma = \frac{\mathrm{d}\mathbf{r}}{\mathbf{r} \ \mathrm{d}\theta} = \frac{\mathbf{s}}{\mathbf{s}'} \tag{60}$$

The current density is given by

$$|j| = \sqrt{j_r^2 + j_\theta^2} \tag{61}$$

To obtain more accurate values of  $j_0$ , the current density at the emitter, the current density  $j_a$  at the collector was first calculated from equation (61). The current density at the emitter was then calculated from

$$j_{o} = j_{a} \left(\frac{r}{r_{o}}\right) = \frac{4}{9} \epsilon_{o} \sqrt{\frac{2q}{m}} \frac{\Phi^{3/2}}{r_{o}^{2}} s(\alpha_{2} - \alpha_{1})$$
 (62)

The solutions of ion trajectories and the angle between the trajectories and the normals to the equipotentials are presented in figures 15 and 16, respectively. A nomogram of equation (62) is given in figure 17. The normalized potential distribution as a function of normalized angle  $(\theta - \alpha_1)/(\alpha_2 - \alpha_1)$  for several angles  $(\alpha_2 - \alpha_1)$  is shown in figure 18.

#### Partial Space-Charge Flow

As early as 1920, Jaffe considered the plane diode under partial space-charge conditions where the current is less than space-charge limited, sometimes called temperature or flow-rate-limited condition, (ref. 14). Since that time there have been several papers on this subject, two of which will be noted here. Brubaker (ref. 15) and Ivey (ref. 16) derived the equations governing the flow of electrons or ions under partial space-charge conditions independently at about the same time. Brubaker made use of normalized variables representing current density, voltage, distance, and emitter field, so that these variables range between zero and unity as the current density varies from zero to the space-charge-limited value. He defined the normalized variables as

$$\bar{j} = \frac{\text{Current density}}{\text{Space-charge-limited current density}} = \frac{j}{j_s}$$

$$\overline{V} = \frac{\text{Voltage at distance } X \text{ from emitter}}{\text{Voltage at collector, at distance } X_a \text{ from emitter}} = \frac{V_x}{V_a}$$

$$\overline{X} = \frac{\text{Distance from emitter}}{\text{Emitter-collector spacing}} = \frac{X}{X_{A}}$$

$$\frac{1}{\gamma} = \frac{\text{Gradient at emitter under influence of space charge}}{\text{Gradient at emitter in absence of space charge}} = \left(\frac{X_a}{V_a}\right) \left(\frac{dV}{dX}\right)_{X=0}$$

The previously mentioned assumption still holds, namely, zero velocity of the particles at the emitter.

The potential distribution and electric field are fully defined by equations (63) and (64):

$$16(\overline{j}\overline{V}^{3/2} - \overline{j}^2\overline{X}^2) = 27(\overline{V}\overline{\gamma}^2 - \overline{X}\overline{\gamma}^3) \tag{63}$$

$$\frac{\overline{dV}}{\overline{dx}} = \frac{27\overline{\gamma}^3 - 32\overline{j}\overline{x}}{27\overline{\gamma}^2 - 24\overline{j}\overline{v}^{1/2}}$$
(64)

The relation between the current density  $\overline{j}$  and the electric field at the emitter is given by equation (63). By setting  $\overline{V} = \overline{X} = 1$  the condition at the collector is given by

$$\vec{j} = \frac{1}{2} + \left(\frac{1}{2} - \frac{3}{4}\,\vec{\gamma}\right)(3\vec{\gamma} + 1)^{1/2}$$
 (65)

Equation (65) is plotted in figure 19. It is interesting to see that the emitter field rises rapidly as the current is decreased from space-charge-limited values. Decreasing the current 10 percent from the space-charge-limited value causes the field to increase from zero to more than 25 percent of its value in the absence of space charge.

If equation (63) is solved for specific values of the electric field  $\overline{\gamma}$  and the current density  $\overline{j}$  or, in other words, if  $\overline{\gamma}=\gamma_0$  and  $\overline{j}=\overline{j}_0$  are held constant, equation (63) gives a relation between  $\overline{V}$  and  $\overline{X}$ . By substituting  $\overline{\gamma}_0$  and  $\overline{j}_0$  into (63) and rearranging terms, equation (63) becomes

$$\overline{X} = \frac{27\overline{\gamma}_{0}^{3}}{32\overline{j}_{0}^{2}} \left[ 1 + \left( \frac{8\overline{j}_{0}\overline{v}^{1/2}}{9\overline{\gamma}_{0}^{2}} - 1 \right) \left( \frac{16\overline{j}_{0}\overline{v}^{1/2}}{9\overline{\gamma}_{0}^{2}} + 1 \right)^{1/2} \right]$$
(66)

Equation (66) is plotted in figure 20. It is seen that the maximum depression of the space potential for space-charge-limited conditions  $(\bar{j}_0=1)$  occurs at  $\bar{x}=27/64$  where the normalized slope is unity. By using the data obtained in figures 19 and 20 in equation (64) the electric field is obtained as a function of position. This is presented in figure 21. The normalized gradient is equal to unity in the plane  $\bar{x}=27/64$  independent of the current density  $\bar{j}$ . As Brubaker points out, this is only an approximation. However, the maximum deviation from unity is only 0.6 percent as the current density is varied from zero to space-charge-limited values.

Ivey investigated the case of a cylindrical diode under partial space-charge conditions (ref. 16). In this case Poisson's equation cannot be integrated directly so a differential analyzer was used to obtain a numerical solution. Without a rigorous proof, Ivey then states that it appears that the emitter field characteristic as shown in figure 19 is "universal" and applies also to other geometries, including those with external emitters. He points out also that this seems to be a direct consequence of Poisson's equation, and the only restrictions on the applicability of figure 19 are those of negligible initial velocities and an equipotential emitter (the same conditions imposed on the generalized space-charge law).

#### THEORY OF PIERCE ELECTRODE DESIGN

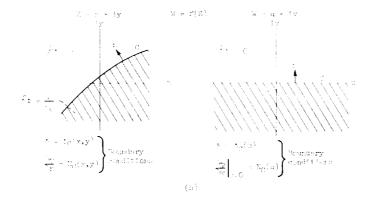
The problem of design of electrode systems that will constrain an accelerating ion beam to travel in a desired region has confronted scientists and engineers for many years. Before 1940 most electrode systems

were designed using assumptions of either zero space charge or paraxial flow. Since then much progress has been made toward the development of general methods for the design of electrodes for high-charge-density ion beams. These methods can be divided into two categories:

- (1) Analog methods such as the resistance network and electrolytic tank
- (2) Analytic solution of the space-charge equations and of Laplace's equation in the region surrounding the ion beam

The most widely used analytic approach to accelerator design was proposed by Pierce (ref. 17) in 1940. Although the Pierce method was originally intended for rectilinear flow, it has since been generalized to include any type of curvilinear flow provided the boundary conditions are regular (ref. 18). When the solution to a particular type of space-charge flow (such as those described in the first section of this report) is found, it generally will fill all space. To form a beam it is necessary to take a segment of this flow and replace the missing portion with an electric field that will exactly match the conditions along the streamlines bounding the ion beam. This is done by arranging suitably shaped electrodes around the ion beam. The electrode shapes are found by solving Laplace's equation in the charge-free space surrounding the ion beam subject to the conditions of continuity of potential and normal gradient across the beam edge.

When the space-charge flow can be expressed in terms of some type of cylindrical coordinate system, as is frequently the case, application of complex variable theory becomes quite useful. This is demonstrated in sketch (h). Curve C represents the boundary of a general curvilinear ion beam that extends to infinity normal to the paper. If an analytic function can be found which transforms C into the u-axis, then the potential distribution along C and the gradient normal to C will be transformed as shown.



Since harmonic functions remain harmonic under conformal transformation, a solution of Laplace's equation for the upper half of the W-plane can be converted to the desired solution in the Z-plane by application of the inverse transformation. A general solution of Laplace's equation in the upper-half plane subject to Cauchy boundary conditions is given in reference 19:

$$\Phi(\mathbf{u}, \mathbf{v}) = \operatorname{Re}\Phi_{\mathbf{C}}(\mathbf{W}) + \operatorname{Im} \int_{\mathbf{C}}^{\mathbf{W}} \mathbf{N}_{\mathbf{C}}(\zeta) d\zeta$$
 (67)

where

Re real part

Im imaginary part

 $\Phi_{C}$  potential distribution along v = 0

 $N_{C}$  potential gradient normal to  $v = O\left(\frac{d\phi}{dv}\right)_{v=0}$ 

In the event that N<sub>C</sub> cannot be integrated explicitly as an analytic function of W, another technique described by Lomax (ref. 18) may be used to obtain  $\Phi(u,v)$ .

It can be seen from equation (67) that  $\Phi(u,v)$  can be written as the real part of a complex function:

$$\Lambda = \Phi + i\Psi = \Phi_{\mathbf{C}}(\mathbf{W}) - i \int_{\mathbf{O}}^{\mathbf{W}} N_{\mathbf{C}}(\zeta) d\zeta$$
 (68)

Hence,

$$\frac{d\Lambda}{dW} = \frac{d\Phi_{\rm C}}{dW} - iN_{\rm C}(W) \tag{69}$$

By application of the Cauchy-Riemann conditions

$$\frac{d\Lambda}{dW} = \frac{\partial\Phi}{\partial u} - \frac{\partial\Phi}{\partial v} = -E_u + iE_v$$

where  $E_u$  and  $E_v$  are the electric field components in the u and v directions transformed from the Z-plane by the mapping function W=f(Z).

Specifically,  $E_{\rm u}$  corresponds to the electric field tangent to the beam edge and  $E_{\rm v}$  corresponds to the field normal to the beam edge.

Since  $E_{\rm u}$  and  $E_{\rm v}$  are derivable from an analytic function, they are differentiable; and the differential equation of a line of electric flux can be written:

$$\frac{\mathrm{d}\mathbf{v}}{\mathrm{d}\mathbf{u}} = \frac{\mathbf{E}_{\mathbf{v}}}{\mathbf{E}_{\mathbf{u}}} \qquad \mathbf{E}_{\mathbf{u}} \neq \mathbf{0} \tag{70}$$

The equipotentials are orthogonal to the lines of force and are therefore determined by the equation

$$\frac{\mathrm{d}\mathbf{v}}{\mathrm{d}\mathbf{u}} = \frac{\mathbf{E}_{\mathbf{u}}}{\mathbf{E}_{\mathbf{v}}} \qquad \mathbf{E}_{\mathbf{v}} \neq 0 \tag{71}$$

The condition  $E_V \neq 0$  is always satisfied in cases of interest since  $E_V = -N_C(u)$ . By taking the real and imaginary parts of equation (69), equation (71) can be written:

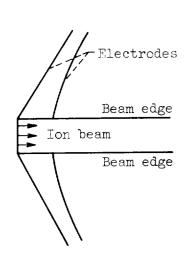
$$\frac{\mathrm{d}v}{\mathrm{d}u} = \frac{\left[\operatorname{Re}\frac{\mathrm{d}\Phi_{\mathbf{C}}}{\mathrm{d}W} + \operatorname{Im}N_{\mathbf{C}}(W)\right]}{\left[\operatorname{Im}\frac{\mathrm{d}\Phi_{\mathbf{C}}}{\mathrm{d}W} - \operatorname{Re}N_{\mathbf{C}}(W)\right]} = \cot\left(\arg\frac{\mathrm{d}\Lambda}{\mathrm{d}W}\right)$$
(72)

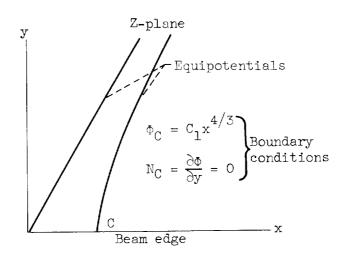
This is the differential equation specifying the equipotential surfaces.

While this technique is applicable to a large number of geometries, there are some configurations of interest that cannot be handled in this way. An example of one of these is rectilinear flow with circular cross section. The solution of this particular problem will be discussed later.

Electrodes for Rectilinear Flow (
$$N_{\rm C}$$
 = O)

Rectilinear slab beam. - This is an application of the solution of flow between infinite parallel planes to the formation of a finite slab ion beam as shown in sketch (i).





Electrode configuration

Mathematical model

From equation (25) the potential distribution along the beam edge is

(i)

$$\Phi_{C} = C_{1}x^{4/3}$$

$$C_{1} = 6.942 \times 10^{4} \text{ A}^{1/3} \text{j}^{2/3}$$
(73)

There is no need for conformal mapping since the beam edge already coincides with the real axis. The boundary conditions to be satisfied are shown in sketch (i). The potential gradient normal to the beam edge  $N_{\rm C}$  is zero. Therefore, equation (67) has the particularly simple form:

$$\Phi = \text{Re}\Phi_{C}(Z) = C_{1}\text{Re}Z^{4/3}$$

$$= C_{1}(x^{2} + y^{2})^{2/3} \cos\left(\frac{4}{3} \tan^{-1} \frac{y}{x}\right)$$
(74)

Equation (74) is developed in dimensional form for clarity. It is much more convenient, however, to nondimensionalize from the start. This may be done by letting X=x/l, Y=y/l, and  $X=\Phi_{\mathbb{C}}/(\mathbb{C}_1 l^{4/3})$  where l is the unit of length. Then equation (73) becomes

$$x = x^{4/3} \tag{75}$$

Sketch (i) remains the same except that now the boundary conditions are:

$$\chi_{\rm C} = X^{4/3} \tag{75}$$

$$\mathbb{N}^{C} = \frac{\partial \lambda}{\partial x} \bigg|^{\lambda = 0} = 0$$

and equation (74) becomes

$$X = \text{Re}(X + iY)^{4/3} = (X^2 + Y^2)^{2/3} \cos\left(\frac{4}{3} \tan^{-1} \frac{Y}{X}\right)$$
 (76)

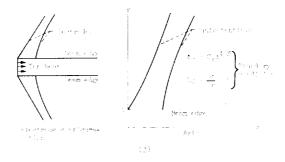
Equipotentials defined by equation (76) are plotted in figure 22 and tabulated in table TV. Note that the  $\chi=0$  electrode makes an angle of  $67.5^{\circ}$  with the beam edge. This is called the Pierce angle, and it occurs in every geometry because, as the ion emitter is approached closer and closer, the potential distribution approaches that of a plane diode. The function  $X^{4/3}$  is multiple-valued and hence can give rise to solutions that do not satisfy the boundary conditions. While it is a simple matter to choose the proper solution in this case, it is not so simple in some of the cases that follow where the complex potential function is a power series. The coordinates listed in table TV agree with the curves shown by Pierce in reference 17.

Beams of circular cross section. - The potential distribution has the same form as equation (73), but in this case polar coordinates are used and x is replaced by z:

$$\Phi_{C} = C_{1}z^{4/3}$$

$$C_{1} = 6.942 \times 10^{4} A^{1/3}j^{2/3}$$
(77)

In 1955 a paper by Daykin (ref. 20) appeared in which a solution to this problem was described. A sketch of the problem is shown as follows:



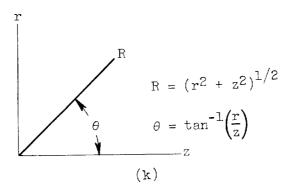
Equation (77) can be nondimensionalized by writing

$$\chi_{C} = \frac{\Phi_{C}}{C_{1}a^{4/3}} = \left(\frac{z}{a}\right)^{4/3} \tag{78}$$

where a is the radius of the ion beam. Daykin showed that the potential distribution near the beam edge can be expressed by an infinite series of the form

$$\chi = \left(\frac{z}{a}\right)^{4/3} \left[1 + \left(\frac{a}{z}\right)^2 F_2\left(\frac{r}{a}\right) + \left(\frac{a}{z}\right)^4 F_4\left(\frac{r}{a}\right) + \dots\right]$$
 (79)

The functions  $F_2$  and  $F_4$  are plotted in figure 23. Because of its rapid convergence near the beam edge, this series may be truncated at three terms without introducing serious error. In order to extend the solution away from the beam edge the asymptotic forms of the equipotentials are computed. For this purpose it is convenient to define a new coordinate system in terms of r and z. This is shown in sketch (k).



The equipotentials are then written in terms of Legendre functions  $P_{4/3}$  of order 4/3 as

$$\chi = \left(\frac{R}{a}\right)^{4/3} P_{4/3}(\cos \theta) \tag{80}$$

Equation (80) is used to obtain electrode shapes far from the beam edge. Equipotentials from equations (79) and (80) are plotted in figure 24(a) and tabulated in tables V and VI. The transition region is shown by dotted lines.

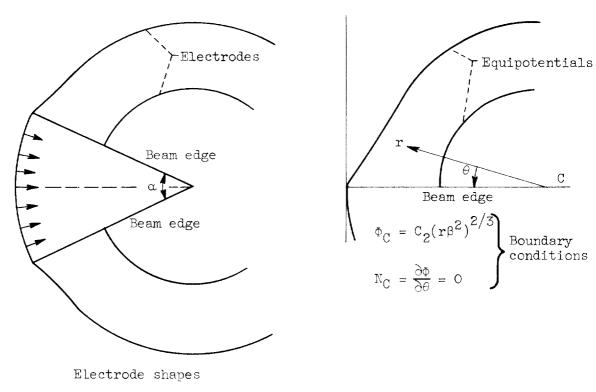
For a hollow ion beam another set of electrodes is required inside the beam. Daykin derived an expression for these equipotentials for small r/b where b is the inner radius of the beam. This equation may be written

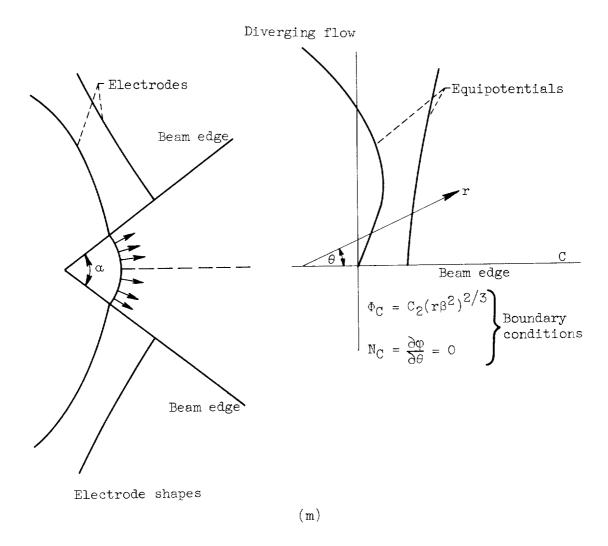
$$\frac{\mathbf{r}}{\mathbf{b}} = \exp \left[-\left(\frac{9}{2}\left(\frac{\mathbf{z}}{\mathbf{b}}\right)^{2}\left[1 - \left(\frac{\mathbf{b}}{\mathbf{z}}\right)^{4/3}\mathbf{x}\right] + \frac{1}{2}\right] \tag{81}$$

As in the previous case it is necessary to fair in part of the equipotentials. Some of these are shown in figure 24(b) and tabulated in table VII. The dotted portion joins the equipotentials from equation (81) to the proper intercept on the inner beam edge defined by equation (78). Until recently this was the only analytic solution of the Pierce electrode problem for axisymmetric ion beams. Harker (ref. 21) has recently developed a very general method whereby any axisymmetric electrode design problem can be solved with the aid of a digital computer.

<u>Cylindrical flow.</u> - The application of converging and diverging flow between coaxial cylinders is considered in this section. The two configurations are shown in sketches (l) and (m).

#### Converging flow





Since the included angle of the wedge is  $\alpha$ , the current per unit length from equation (28) will be multiplied by the factor  $\alpha/2\pi$ . The potential distribution becomes

$$\Phi_{C} = C_{2}(r\beta^{2})^{2/3}$$

$$C_{2} = 6.942 \times 10^{4} A^{1/3} \left(\frac{J}{\alpha l}\right)^{2/3}$$
(82)

This is nondimensionalized by letting R =  $r/r_0$  and  $\chi_C = \Phi_C/(C_2 r_0^{2/3})$ . The nondimensional potential distribution becomes

$$\chi = (R\beta^2)^{2/3} \tag{83}$$

From equation (29) it follows that

$$(R\beta^2) = \left[\sum_{n=1}^{\infty} B_n (\ln R)^n\right]^2$$

and

$$X = \left[\sum_{n=1}^{\infty} B_n (\ln R)^n\right]^{4/3}$$
(84)

Since the potential gradient  $N_{\rm C}$  normal to the ion beam is zero, the expression for the potential outside of the beam is, from equation (67),

$$X(R,\theta) = Re \left[ \sum_{n=1}^{\infty} B_n \left( ln \frac{Z}{r_o} \right)^n \right]^{4/3}$$
 (85)

where

$$\frac{Z}{r_0} = \frac{r}{r_0} e^{i\theta} = Re^{i\theta} = R(\cos \theta + i \sin \theta)$$

Equation (85) can be rewritten

$$X = (P^2 + Q^2)^{2/3} \cos\left(\frac{4}{3} \tan^{-1} \frac{Q}{P}\right)$$
 (86)

where

$$P = \left[ \ln R + 0.1(\ln^2 R - \theta^2) + 0.0167(\ln R^3 - 3\theta^2 \ln R) + 0.00242(\ln^4 R - 6\theta^2 \ln R + \theta^4) + \dots \right]$$

and

$$Q = \left[\theta + 0.2 \ \theta \ \ln R + 0.0167(3\theta \ \ln^2 R - \theta^3) + 0.00242(4\theta \ \ln^3 R - 4\theta^3 \ \ln R) + \dots\right]$$

Equation (86) was solved for several values of X on a digital computer. Equipotentials for both converging and diverging flow are shown in figures 26 and 27 and are tabulated in tables VIII and IX, respectively. This case was also solved by Radley (ref. 22) for convergent flow, and the results shown in table VII agree with those shown in reference 22.

## Electrodes for Curvilinear Flow (N $_{\rm C}$ $\neq$ 0)

<u>Circular flow.</u> - The space-charge-limited-flow equations for which the ion trajectories are concentric circular arcs are used here in the design of a curved ion beam. This solution was obtained by Lomax in reference 18. The potential distribution obtained from equation (34) is:

$$\Phi_{C} = C_{3}r^{-2} \left( \sin \frac{3\theta}{2} \right)^{4/3} \tag{87}$$

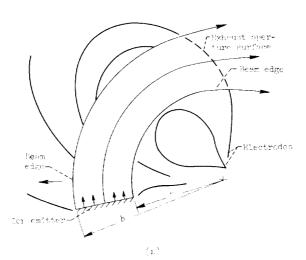
where

$$c_3 = 1.02 \times 10^5 \text{ A}^{1/3} \left( \frac{a^4 b^4}{b^4 - a^4} \right)^{2/3} \left( \frac{J}{\epsilon_0 l} \right)^{2/3}$$

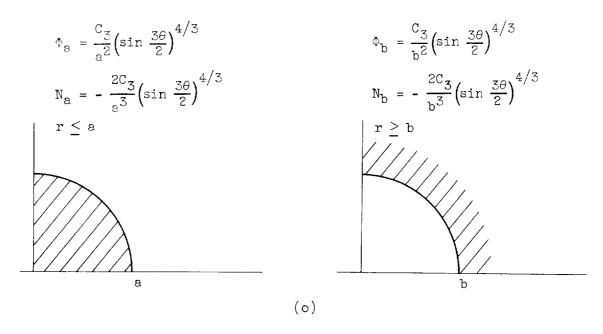
The potential gradient normal to the beam is

$$\frac{\partial \varphi}{\partial \mathbf{r}} = -\frac{\partial \Phi_{\mathbf{C}}}{\partial \mathbf{r}} = \frac{2\mathbf{C}_{\mathbf{3}}}{\mathbf{r}^{\mathbf{3}}} \left( \sin \frac{3\theta}{2} \right)^{4/3} \tag{88}$$

A sketch of the electrode structure is shown as follows:



From the sketch it is seen that the problem can be divided in two parts:  $r \ge b$  and  $r \le a$ . Sketches for these two problems together with the corresponding boundary conditions are shown as follows: (The shaded region is the region of interest in each case.)



In this case it is necessary to map the beam edge onto the real axis. Lomax shows that a mapping function that will do this is (for r = b)

$$Z = be^{iW}$$
 (89)

The boundary conditions become, on v = 0,

$$\Phi_{C}(u) = \frac{c_3}{b^2} \left( \sin \frac{3u}{2} \right)^{4/3}$$

$$N_{C}(u) = \frac{2C_{3}}{b^{2}} \left(\sin \frac{3u}{2}\right)^{4/3}$$

The formal solution of Laplace's equation in the upper half of the W-plane is given by equation (67), which becomes

$$\Phi(u,v) = \text{Re} \, \frac{C_3}{b^2} \left( \sin \frac{3W}{2} \right)^{4/3} + \text{Im} \int_0^W \frac{2C_3}{b^2} \left( \sin \frac{3\zeta}{2} \right)^{4/3} d\zeta \tag{90}$$

Explicit integration of the second term is not readily carried out; therefore, the differential equation representing the equipotentials must be solved. By combining equations (69), (72), and (90), the differential equation becomes

$$\frac{\mathrm{d}\mathbf{v}}{\mathrm{d}\mathbf{u}} = \cot\left[\frac{1}{3}\tan^{-1}\left(\frac{\tanh\frac{3}{2}\mathbf{v}}{\tan\frac{3}{2}\mathbf{u}}\right) - \frac{3}{2}\mathbf{u}\right] \tag{91}$$

From the transformation equation (89) it follows that

$$R = \frac{r}{b} = e^{-V}$$

and

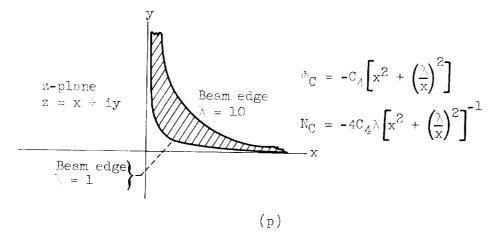
$$\theta = u$$

Equation (91) becomes in the Z-plane

$$R \frac{d\theta}{dR} = \tan \left[ \frac{3}{2} \theta - \frac{1}{3} \tan^{-1} \left( \frac{1 - R^3}{1 + R^3} \right) \cot \frac{3\theta}{2} \right]$$
 (92)

Equation (92) was integrated using the Runge-Kutta method, and some typical equipotentials are shown for a/b = 0.7 in figure 27 and are tabulated in tables X and XI. The inside equipotentials were found by simply replacing b by a in equations (89) and (92). In figure 27  $X_b = \Phi(b^2/C_3)$  and  $X_a = \Phi(a^2/C_3)$ . These results agree with those obtained by Lomax in reference 18.

Electrodes for hyperbolic flow. Sketch (p) shows a segment of hyperbolic flow bounded by the curves y = 1/x and 10/x. This solution was obtained by Rosenblatt in reference 12.



The potential distribution along the beam edge as given in the space-charge-flow section is

$$\Phi_{\mathbb{C}} = -C_4 \left[ x^2 + \left( \frac{\lambda}{x} \right)^2 \right]$$

where

$$C_4 = 1.60 \times 10^4 A^{1/3} \left( \frac{J}{\lambda l} \right)^{2/3}$$

and

$$\lambda = 1,10$$

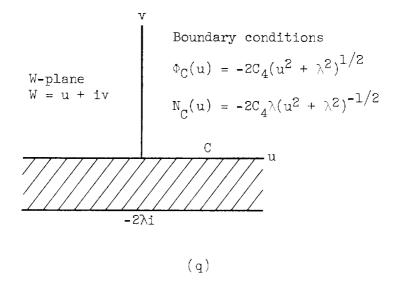
The solution of Laplace's equation outside the ion beam in the upper part of the first quadrant (i.e., outside the boundary  $\lambda$  = 10) will be obtained first. It is shown in reference 12 that a transformation that will map the beam boundary onto the real axis is:

$$W = \frac{1}{2} (Z^{2} - 2i\lambda) = u + iv$$

$$u = \frac{1}{2} (x^{2} - y^{2})$$

$$v = xy - \lambda$$
(93)

A sketch of the transformed boundary is shown as follows:



The transformed boundary conditions are also shown. Equation (67) may now be used:

$$\phi(u,v) = \text{Re}\left[-2\lambda(W^2 + \lambda^2)^{1/2}\right] + \text{Im} \int_0^W \left[-2c_4\lambda(\zeta^2 + \lambda^2)^{-1/2}\right] d\zeta$$
 (94)

After integration and separation of the real and imaginary parts the equipotentials in the W-plane are expressed by:

$$\Phi(\mathbf{u}, \mathbf{v}) = -2C_4 \left( \frac{1}{\sqrt{2}} \left\{ \left[ (\mathbf{u}^2 + \lambda^2 - \mathbf{v}^2)^2 + 4\mathbf{u}^2\mathbf{v}^2 \right]^{1/2} + (\mathbf{u}^2 + \lambda^2 - \mathbf{v}^2) \right\}^{1/2} \right.$$

$$+ \lambda \tan^{-1} \frac{\mathbf{v} + \frac{1}{\sqrt{2}} \left\{ \left[ (\mathbf{u}^2 + \lambda^2 - \mathbf{v}^2)^2 + 4\mathbf{u}^2\mathbf{v}^2 \right]^{1/2} - (\mathbf{u}^2 + \lambda^2 - \mathbf{v}^2) \right\}^{1/2}}{\mathbf{u} + \frac{1}{\sqrt{2}} \left\{ \left[ (\mathbf{u}^2 + \lambda^2 - \mathbf{v}^2)^2 + 4\mathbf{u}^2\mathbf{v}^2 \right]^{1/2} + (\mathbf{u}^2 + \lambda^2 - \mathbf{v}^2) \right\}^{1/2}} \right)$$
(95)

This equation may be nondimensionalized by dividing equation (95) by  $-c_4\lambda$ . Substitution of the values of u and v from equation (93) yields the expression for the electrode shapes in the (x,y) plane. Some of these are plotted in figure 28. Equipotentials outside the beam edge  $\lambda = 1$  may be obtained by the mapping  $W = \frac{1}{2} (2i\lambda - Z^2)$ . The potential function is identical to equation (95) except for minus signs in front of the nonsquared u and v in the arc tangent term. Some electrode shapes for this boundary are also shown in figure 28.

Since there is no zero velocity surface in this configuration, it may not have any practical application. It may possibly be used to deflect an ion beam, however.

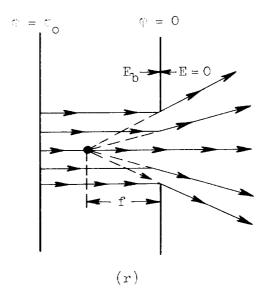
# Limitations of the Pierce Technique

The departure of analytically derived ion accelerators from physical fact lies mainly in two areas. The first of these is that practical requirements dictate modifications in the calculated electrode shapes. These modifications manifest themselves in the curtailment of electrode size and the insertion of apertures in the electrodes to pass the ion beam. The inherent instability in the solution of elliptic differential equations with Cauchy boundary conditions on open boundaries works in reverse to minimize the error caused by curtailment or modification of electrode shapes away from the boundary. This means that, while small variations of potential along the boundary will cause increasingly larger variations the farther away from the boundary, conversely, large variations far away from the boundary cause only small variations along the boundary. This is readily observed in an electrolytic tank where a tremendously wide variety of electrode shapes will give the proper potential distribution along the beam edge to within the accuracy of the measuring equipment. It is difficult to give exact numbers for the magnitude of this effect other than to say that the error propagates away from the boundary approximately as eKy, where y is the distance measured from the boundary and K is a constant.

Aperture effect. - Insertion of apertures in the electrodes has two deleterious effects on ion accelerator performance. The first is that the aperture acts as an electrostatic lens which will tend to diverge an accelerating ion beam. If multiple electrodes are being used, this results in impingement of ions on the electrodes. Even if only one accelerating electrode is used, the formation of a diverging ion beam will result and may cause some impingement on this electrode. It is shown in reference 23 that the focal length of an aperture is

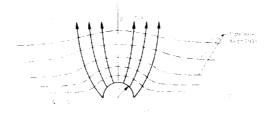
$$f = \frac{-2g\Phi}{E_h} \tag{96}$$

where g=1 for slits, g=2 for circular apertures, and  $E_{\tilde{D}}$  is the negative potential gradient on the upstream (or source) side of the aperture. The meaning of this is demonstrated in sketch (r).



The second effect is to reduce the ion current by increasing the effective accelerating distance. Depending on the ratio of aperture width to accelerating distance, experimentally observed current densities can be a small fraction of the theoretically expected values.

Emitting surface irregularities. - The second area of departure of the Pierce theory from physical fact lies in the assumptions regarding initial conditions at the ion emitter. The usually assumed condition of zero initial velocity along a perfectly smooth equipotential surface is not met in practice, and it will be shown that considerable error can arise as a result of this. Rather than treat these effects separately, the nature of the ion trajectories in the neighborhood of a rough emitter will be investigated, and dispersion due to transverse electric fields will be compared directly with thermal spreading. In order to do this it is first necessary to examine the potential distribution near a surface irregularity. A sketch of the mathematical model is shown as follows:



The surface irregularity is a cylindrical hump of radius l, and it is assumed that at 100 units above the hump the equipotentials are essentially plane. An approximate expression for a flux line as computed in appendix B is  $(u/l) = (x/l)\{1 + 1/[(x/l)^2 + (y/l)^2]\}$ . The bounding flux line, which originates at the point x = l, y = 0, is (u/l) = 2. This line intersects the line y = 100l at  $x \approx 2l$ . Hence, the flux line spreading due to the electrostatic field of the hump is  $\Delta x \approx l$ . It is shown in appendix B that thermal spreading  $\Delta x_T$  at y = 100l, which is the product of the most probable thermal velocity and the ion transit time, can be written  $\Delta x_T = 200l\sqrt{0.1/\phi_0}$  where the effective thermal potential is assumed to be 0.1 volt. The ratio of electrostatic to thermal spreading is

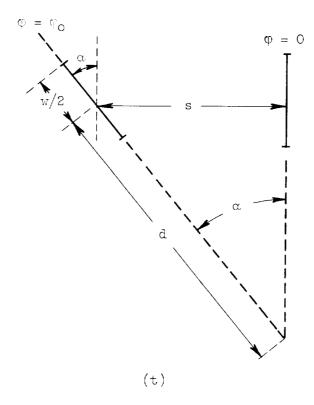
$$\frac{\Delta x}{\Delta x_{\rm T}} = \sqrt{\frac{\varphi_{\rm O}}{4 \times 10^3}} \tag{97}$$

The macroscopic electric field strength E in an ion rocket is defined as the applied accelerating voltage divided by the accelerator spacing. For emission-limited flow E usually has a value of between  $10^5$  and  $10^7$  volts per meter. From sketch (s) it can be seen that the voltage across the model  $\phi_{\rm O}$  can be written  $\phi_{\rm O}$  = E(1001), and the spreading ratio becomes

$$\frac{\Delta x}{\Delta x_{rp}} = \sqrt{\frac{E7}{40}} \tag{98}$$

Equation (98) is shown plotted in figure 29. It is seen from figure 29 that spreading due to the electrostatic field of a surface irregularity can be of the same order of magnitude as thermal spreading. It should be noted that this analysis is based on zero space charge and therefore is only approximate.

Analysis of accidental misalinement of parallel planar electrodes. - As pointed out by Ivey (ref. 10), an accidental misalinement of parallel planar electrodes can be analyzed as an application of the motion between two inclined planar electrodes. Consider the electrode arrangement as shown in sketch (t):



One electrode is tilted about its center by an angle  $\,\alpha\,$  from the parallel condition and

$$d = \frac{s}{\sin \alpha}$$

The current per unit length when  $\alpha = 0$  may be written

$$\frac{J_{\alpha=0}}{l} = \frac{4}{9} \in O\left(\frac{2q}{m}\right)^{1/2} \frac{\Phi^{3/2}w}{s^2}$$
(99)

and thus the ratio  $\mathrm{J}/\mathrm{J}_{\alpha=0}$ , which gives the effect of the tilt, is

$$\frac{J}{J_{\alpha=0}} = \frac{H(\alpha)}{\left(\frac{1}{\sin \alpha}\right)^2 - \left(\frac{w}{2s}\right)^2}$$
(100)

Values from equation (100) were calculated by Ivey for small angles of  $\alpha$  and are presented in figure 30. For a rectangular emitter with an aspect ratio of w/s = 1.24, the current per unit length is insensitive to the angle of tilt about a line passing through its center and parallel

to its side. Ivey also showed the independence of angular misalinement in an arbitrary direction by the use of a disk-shaped emitter. The total current for  $\alpha$  = 0 in this case is

$$J_{\alpha=0} = \frac{4}{9} \epsilon_0 \left(\frac{2q}{m}\right)^{1/2} \frac{\Phi^{3/2} \pi D^2}{4s^2}$$
 (101)

where D is now the diameter of the disk, and the effect of electrode tilt becomes

$$\frac{J}{J_{\alpha=0}} = 8G(\alpha) \left(\frac{s}{D}\right)^2 \left\{ \frac{1}{\left[1 - \left(\frac{D \sin \alpha}{2s}\right)^2\right]^{1/2}} - 1 \right\}$$
 (102)

Values from equation (102) were also calculated by Ivey and are presented in figure 31. It is seen that the variation of current for the aspect ratio D/s = 1.42 is zero. For this optimum geometry (aspect ratio D/s = 1.42) equation (101) becomes

$$J_{\alpha=0} = 6.233 \times 10^{-12} \left(\frac{2q}{m}\right)^{1/2} \Phi^{3/2}$$
 (103)

and the behavior of  $J/J_{\alpha=0}$  for the above optimum geometry is shown in figure 31. It is seen that even a large angle of tilt does not change the total current appreciably. This, of course, does not mean that the ion optics will not be affected, and in an ion rocket the ion impingement on the electrodes must be reduced to nearly zero for long-duration operation. Therefore, electrode alinement is still quite critical.

## CONCLUDING REMARKS

Three methods for the analytic solution of the space-charge-flow problem appear in the literature, in which certain properties of the flow are prescribed. These are (1) initial and final equipotentials, (2) velocity and acceleration, and (3) trajectories and action function. None of these methods is generally applicable at present. Of the three methods, the trajectory-action function method appears the most versatile for the design of electrostatic rocket engine accelerators.

The existing solutions of space-charge flow have been described, and the parameters pertinent to the design of electrostatic rocket engine accelerators have been given for the following geometries: (1) paraxial

flow, (2) flow between coaxial cylinders, (3) flow between concentric spheres, (4) circular flow, (5) hyperbolic flow, (6) flow between inclined planes, and (7) flow between coaxial cones.

Electrode shapes determined by the method of Pierce have been given for the following geometries: (1) rectilinear flow with rectangular cross section, (2) paraxial flow with circular cross section, (3) convergent flow between coaxial cylinders, (4) divergent flow between coaxial cylinders, (5) circular flow, and (6) hyperbolic flow.

Limitations of the space-charge-flow and electrode design theories have been discussed. One is the aperture effect and another is the effect of irregularities on the ion emitting surface. Surface irregularities have been demonstrated to cause lateral ion velocity components of the same order of magnitude as thermal ion velocities.

Lewis Research Center
National Aeronautics and Space Administration
Cleveland, Ohio, August 20, 1962

# APPENDIX A

# SYMBOLS

(mks units used throughout.)

	,
А	molecular weight/ionic charge (ionic charge may be greater than one in multiply charged ions)
a	inner radius of circular ion beam; outer radius of ion beam with circular cross section
В	$(h_2h_3/h_1)\nabla^2(1/h_1^2)$
ъ	outer radius of circular ion beam; inner radius of ion beam with circular cross section
C	$h_2h_3/h_1^5$ ; also ion beam edge
$\mathbf{c}_1, \mathbf{c}_2, \mathbf{c}_3, \mathbf{c}_4$	constants identified in text
D	diameter of disk emitter
đ	$S/\sin \alpha$ , for electrode tilt analysis
E	electric field strength, volts/meter
е	unit electronic charge, 1.602×10 <sup>-19</sup> coulomb
$F_2, F_4$	dimensionless functions of $r/a$ defined in ref. 16
$F(\alpha)$	function defined in eq. (50)
g(θ)	function defined in eq. (43)
g <sub>c</sub>	gravitational conversion factor, 9.806 meters/sec <sup>2</sup>
H(a)	function defined in eq. (100)
h <sub>1</sub> ,h <sub>2</sub> ,h <sub>3</sub>	scale factors in curvilinear coordinates, $ds^2 = h_1^2 d\xi^2 + h_2^2 d\eta^2 + h_3^2 d\zeta^2$
Im	imaginary part
J	total current, amp

```
current per unit length, amp/meter
J/l
                current density, amp/meter<sup>2</sup>
               (h_2h_3/\epsilon_0)j\sqrt{m/2q}
K(\eta, \zeta)
                accelerator height, meters; also unit of length
7
                particle mass, kg
                potential gradient normal to boundary C
N_{\rm C}
                charge, coulombs
q
                r/r_o, r/r_a, r/r_h
R
                real part
Re
                radius as in spherical and cylindrical polar coordinates
\mathbf{r}
                emitter radius; also initial radius of trajectory in flow
r_{0}
                  between inclined planes; also inner radius in circular
                  flow engine
                accelerating distance for electrode tilt analysis
S
                function defined in eq. (52)
s(\theta)
ds
                differential displacement along a trajectory
                coordinates in W-plane (W = u + iv)
u, v
                ion velocity
                velocity components in Cartesian coordinates
v_x, v_y, v_z
                velocity components in polar coordinates
v_{r}, v_{\theta}
÷
v
                acceleration vector
                most probable thermal velocity
\overline{v}
                action function, meter^3/\text{sec}; also complex number u + iv
W
                tilt analysis
\overline{W}
                nondimensional Cartesian coordinates
X,Y
```

```
Cartesian coordinates
x, y, z
y(θ)
                function defined in eq. (39)
Ζ
                x + iy
\overline{Z}
                x - iy
                Langmuir function for spheres; angle between inclined
\alpha
                   planes; arbitrary fixed angle
                conical half-angles
\alpha_{7}, \alpha_{2}
β
                Langmuir function for cylinders
                h_1^2\Phi
Γ
                angle between ion trajectory and flux line in flow between
Υ
                   coaxial cones
                permittivity of free space, 8.855x10<sup>-12</sup>
\epsilon_{o}
                   coulomb/(newton)(meter<sup>2</sup>)
                curvilinear coordinate defining trajectories
ζ,η
θ
                angular displacement, deg
                complex potential function, \Phi + i\Psi
Λ
                hyperbolic trajectory parameter
λ
                curvilinear coordinate defining action function
ξ
                charge density, coulomb/meter<sup>3</sup>
ρ
                \varphi_{O} - \varphi
Φ
                potential distribution along beam boundary
\Phi_{\mathbf{C}}
                angular displacement in spherical coordinates; also poten-
Φ
                  tial, volts
                emitter potential, volts
φο
χ
                nondimensional potential distribution
```

 $\Psi$  flux line

 $\ensuremath{\omega}$  angle between ion trajectory and flux line for flow between coaxial cones

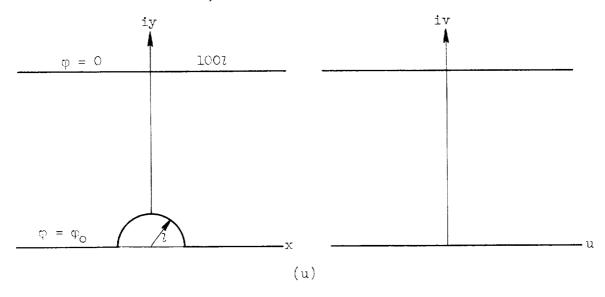
# Superscripts:

',","',"'' differentiation with respect to variable  $\theta$ 

#### APPENDIX B

## APPROXIMATE ION BEAM DISPERSION DUE TO SURFACE ROUGHNESS

In this appendix the electric field in the neighborhood of a cylindrical hump will be obtained. Following that the transit time of an ion through the diode will be calculated, and an expression for thermal spreading, which is the product of the most probable thermal velocity and the ion transit time, will be shown.



The surface is an infinite plane containing a cylindrical hump of radius  $\it{l.}$  It is assumed that at a distance  $\it{y}=100\it{l.}$  the equipotential surfaces are plane. By the conformal transformation  $\it{w}=\it{z}+\it{l/z}$  the system is converted into two plane electrodes separated by a distance of 99.99  $\it{l.}$  This is shown on the right side of sketch (u). The spacecharge-free potential distribution in the W-plane is

$$\varphi(u, v) = \varphi_0 \left(1 - \frac{v}{99.99 l}\right)$$
 (B1)

The electric field is obtained by differentiation of equation (B1) with respect to v:

$$E = -\frac{d\phi}{dv} = \frac{\phi_{O}}{99.99 \ 1}$$
 (B2)

Returning to the right side of sketch (u) the flux lines are given by u/l=constant. From the transformation equation the expression for u/l is

$$\frac{u}{l} = \frac{x}{l} \left[ 1 + \frac{1}{\left(\frac{x}{l}\right)^2 + \left(\frac{y}{l}\right)^2} \right]$$
 (B3)

This equation is used in the computation of spreading due to the electric field of a surface irregularity.

In the computation of transit time through the diode in sketch (u) (left side), it is assumed that the electric field is constant; that is,

$$E = \frac{\varphi_0}{1007} \tag{B4}$$

The equation of motion of an ion is

$$m \frac{d^2y}{dt^2} = qE = \frac{q\phi_0}{1001}$$
 (B5)

Integration of equation (B5) subject to the initial conditions of

$$\frac{dy}{dt} \cong 0$$
 at  $t = 0$ 

and

$$y = 0$$
 at  $t = 0$ 

yields

$$y = \frac{q\phi_0}{200ml} t^2$$
 (B6)

At y = 1001 the transit time is

$$t = 1001 \sqrt{\frac{2m}{q\phi_O}}$$
 (B7)

From reference 24 it is seen that the most probable thermal velocity is

$$\overline{v} = \sqrt{\frac{2q\overline{v}}{m}}$$
 (B8)

where  $\overline{\phi}$  is the mean thermal potential (usually taken to be about 0.1 volt). Thermal spreading is then the product of equations (B7) and (B8):

$$\Delta x_{\mathrm{T}} = 2001 \sqrt{\frac{\overline{\varphi}}{\varphi_{\mathrm{O}}}} = 2001 \sqrt{\frac{0.1}{\varphi_{\mathrm{O}}}}$$
 (B9)

## APPENDIX C

#### RESCALING OF NOMOGRAMS

The nomograms shown in this report may be easily rescaled to allow computations beyond the range of one or more of the variables. Consider, for example, the nomogram in figure 1, which represents the space-charge-flow equation for a plane diode. The equation is

$$j = 5.467 \times 10^{-8} A^{-1/2} (\phi_0 - \phi)^{3/2} x^{-2}$$
 (26)

The ranges of the various scales are

$$10 \le A \le 10^{3}$$

$$2 \times 10 \le J \le 10^{3}$$

$$10^{-4} \le x \le 10^{-2}$$

$$10^{2} \le (\phi_{0} - \phi) \le 10^{4}$$

Suppose that it is desired to calculate the current density for heavier particles, say up to  $10^5$  amu. This means that the new range of the A scale will be from  $10^3$  to  $10^5$  amu. It is seen from equation (26) that, if  $(\phi_0 - \phi)$  and x are held constant and if A is multiplied by  $10^2$ , then J will be divided by 10. That is, there exists a scale factor associated with A which, when multiplied by the range of J, will give the new range. In this case,  $K_A = 10^{-1}$  and the new range of J will be

$$2 < J \le 10^2$$

Usually it is necessary to rescale several variables simultaneously. This may be done in a similar manner. Suppose, for instance, that the desired ranges are to be changed in accordance with the following list:

$$10 \le A \le 10^3 \to 10^3 \le A \le 10^5$$
  
 $2 \times 10 \le J \le 10^3 \to ? \le J \le ?$ 

$$10^{-4} \le x \le 10^{-2} \rightarrow 10^{-2} \le x \le 10^{0}$$
$$10^{2} \le (\phi_{0} - \phi) \le 10^{4} \rightarrow 10^{4} \le (\phi_{0} - \phi) \le 10^{6}$$

Referring again to equation (26) it is seen that scaling factors may be assigned to each variable. For instance, it was shown that the scaling factor  $K_A$  due to a hundredfold increase in A is  $10^{-1}$ . The net scaling factor applied to J will be the products of the individual factors. These are

$$K_A = 10^{-1}$$

$$K_{\chi} = 10^{-4}$$

$$K_{\odot} = 10^3$$

and finally

$$K_J = K_A K_{\chi} K_{\varphi} = 10^{-2}$$

Therefore, the new range of the J scale will be

$$2 \times 10^{-1} \le J \le 10$$

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TABLE T. - SPACE-CHARGE-FLOW EQUATIONS FOR SEVERAL GEOMETRIES

	,	,		1	
General equation (24)	$\frac{1}{2} \sqrt{2} \frac{d^2 r}{dx^2} = K(\eta, \xi)$	$e^{-1/2}\left[\frac{\partial}{\partial x}\left(z,\frac{\partial T}{\partial z}\right)\right]=K(\eta,\zeta)$	$\frac{1}{1} J/2 \left[ \frac{\partial}{\partial r} \left( r^2 + r + \frac{\partial r}{\partial r} \right) \right] = \mathcal{I}(r, \zeta)$	** $\frac{1}{1}\sqrt{2}\left[\frac{4^{2}}{4(2)} + 4^{2}\right] = K(\eta, \xi)$	$ \frac{***}{4\pi^{1}} \sqrt{2} \left[ \frac{\partial}{\partial \xi} \left( \xi^{2} + \gamma^{2} \right) \left( \frac{3T}{3\xi} \right) + \pi \right] = \mathcal{Z}(T_{1}, \xi) $
א(ח,ל)	- 13 - 13 - 13 - 13 - 13 - 13 - 13 - 13	8. V (2. V (	m <sup>2</sup> (atr. 9) ( m	- 23	3 Va/29 805(\$2 + 112) 1/2
Đ	r H	£4	क य य	)     \$4	4(\$2 + 72)
ш	0	0	0	24 12 12	4
1:3	а	7	ក ជួន ម	Н	r f
5.5	П	ធ	٤.	r <b>1</b>	3/5 1/8
,e <sup>†</sup>	1	ert	e	ų	1/5 (£\$ + £\$)
8,0	const.	z = const.	; = const.	z =	Z = ccnst.
Ü	45 10 50 50 50 11	χ  4 - 200 - 200 - 4 - 9	2	$x = x = (x^2 + y^2)^{1/2}$	.ex
44.	×	$r = (x^2 + 5^2)^{\frac{1}{2}/2}$	$(x^2 + y^2 + z^2)^{1/2} \theta = c.s^{-1} \frac{z}{r}$	$\theta = \cos^{-1} \frac{x}{r}$	1 (x5 - 32)
ಸು೯೭ ನಂ ಕಮೆ೭	Rectilinear between blane electroles	Recullings concentro cylindrics:	Restillinear Setween consenting sphenium electrodes	G.routar	0 : : : : : : : : : : : : : : : : : : :

\*  $\sqrt{\frac{1}{82}} = 0.7189$ x1074  $\sqrt{A}$ .

\*\*
identical to Neitzep's equation in ref. 10.

\*\*\*
This equation is theated in ref. 11 and in a different fashion in ref. 0.

TABLE II. - LANGMUIR FUNCTION FOR CONCENTRIC CYLINDRICAL FLOW

r/r <sub>o</sub>	β <sup>2</sup>	r/r <sub>o</sub>	β <sup>2</sup>	r/r <sub>o</sub>	β2	r/r <sub>o</sub>	β <sup>2</sup>
0.01000 .01111 .01250 .01429	1174.9000 1018.5000 867.1100 721.4300 582.1400	0.2500 .2632 .2778 .2941 .3125	6.06010 5.37950 4.72980 4.11260 3.52930	1.00 1.01 1.02 1.04 1.06	0.00000 .00010 .00039 .00149 .00324	4.0 4.2 4.4 4.6 4.8	0.6671 .6902 .7115 .7313 .7496
.02000 .02500 .03333 .05000	450.2300 327.0100 214.4200 115.6400 97.9970	.3333 .3448 .3571 .3704 .3846	2.98140 2.72140 2.47080 2.23010 1.99950	1.08 1.10 1.15 1.20 1.30	.00557 .00842 .01747 .02875	5.2 5.4 5.6 5.8	.7666 .7825 .7973 .8111
.06250 .07143 .08333 .10000	81.2030 65.3520 50.5590 36.9760 33.7910	.4000 .4167 .4348 .4545	1.77920 1.56970 1.37120 1.18400 1.00860	1.40 1.50 1.60 1.70	.08672 .11934 .15250 .18540 .21770	6.0 6.5 7.0 7.5 8.0	.8362 .8635 .8870 .9074
.11110 .11760 .12500 .13330 .14290	30.6980 27.7010 24.8050 22.0150 19.3370	.5000 .5263 .5556 .5882 .6250	.84540 .69470 .55720 .43320 .32330	1.90 2.00 2.10 2.20 2.30	.24910 .27930 .30830 .33610 .36260	8.5 9.0 9.5 10.0 12.0	.9410 .9548 .9672 .9782 1.0122
.15380 .16670 .17240 .17860 .18520	16.7770 14.3430 13.4070 12.4930 11.6010	.6667 .7143 .7692 .8333 .8696	.22820 .14856 .08504 .03849 .02186	2.40 2.50 2.60 2.70 2.80	.38790 .41210 .43510 .45710 .47800	14.0 16.0 18.0 20.0 30.0	1.0352 1.0513 1.0630 1.0715 1.0908
.19230 .20000 .20830 .21740 .22730 .23810	10.7330 9.8887 9.0696 8.2763 7.5096 6.7705	.9091 .9259 .9434 .9615 .9804 .9901	.00980 .00630 .00356 .00159 .00040 .00010	2.90 3.00 3.20 3.40 3.60 3.80	.49800 .51700 .55260 .58510 .61480	40.0 50.0 60.0 70.0 80.0 90.0 100.0	1.0946 1.0936 1.0910 1.0878 1.0845 1.0813

TABLE III. - LANGMUIR FUNCTION FOR CONCENTRIC SPHERICAL FLOW

r/r <sub>o</sub>	<sub>α</sub> 2	r/ro	α2	r/r <sub>o</sub>	$\alpha^2$	r/r <sub>o</sub>	$\alpha^2$
0.01000	1144.000	0.2500	4.9680	1.00	0.0000	4.2	0.979
.01111	974.100	.2632	4.4290	1.05	.0023	4.4	1.022
.01250	813.700	.2778	3.9130	1.10	.0086	4.6	1.063
.01429	663.300	.2941	3.4210	1.15	.0180	4.8	1.103
.01667	523.600	.3125	2.9540	1.20	.0299	5.0	1.141
.02000 .02500 .03333 .05000 .05556	395.300 279.600 178.200 93.240 78.560	.3333 .3448 .3571 .3704 .3846	2.5120 2.3020 2.0980 1.9010 1.7120	1.25 1.30 1.35 1.40 1.45	.0437 .0591 .0756 .0931 .1114	5.4 5.6 5.8 6.0	1.178 1.213 1.247 1.280 1.311
.06250	64.740	.4000	1.5310	1.50	.1302	6.5	1.385
.07143	51.860	.4167	1.3580	1.60	.1688	7.0	1.453
.08333	39.980	.4348	1.1930	1.70	.2080	7.5	1.516
.10000	29.190	.4545	1.1036	1.80	.2480	8.0	1.575
.10530	26.680	.4762	.8880	1.90	.2870	8.5	1.630
.11110	24.250	.5000	.7500	2.00	.3260	9.0	1.682
.11760	21.890	.5263	.6210	2.10	.3640	9.5	1.731
.12500	19.620	.5556	.5020	2.20	.4020	10.0	1.777
.13330	17.440	.5882	.3940	2.30	.4380	12.0	1.938
.14290	15.350	.6250	.2968	2.40	.4740	14.0	2.073
.15830	13.350	.6667	.2118	2.50	.5090	16.0	2.189
.16670	11.460	.6897	.1740	2.60	.5430	18.0	2.289
.17240	10.730	.7143	.1396	2.70	.5760	20.0	2.378
.17860	10.010	.7407	.1084	2.80	.6080	30.0	2.713
.18520	9.315	.7692	.0809	2.90	.6390	40.0	2.944
.19230 .20000 .20830 .21740 .22730 .23810	8.636 7.976 7.334 6.712 6.109 5.528	.8000 .8333 .8696 .9091 .9524 1.0000	.0571 .0372 .0213 .0096 .0024	3.00 3.20 3.40 3.60 3.80 4.00	.6690 .7270 .7830 .8360 .8860	50.0 60.0 70.0 80.0 90.0 100.0	3.120 3.261 3.380 3.482 3.572 3.652

TABLE IV. - ELECTRODE COORDINATES

FOR RECTILINEAR SLAB ION BEAM

Y	Х	Х	Х
	X = 0	X = 0.4	X = 1.0
0	0	0	1.0000
.1	.04141	.50626	1.0017
.2	.08283	.51578	1.0066
.3	.12425	.53072	1.0147
.4	.16567	.55009	1.0258
.5 .6 .7 .8	.20708 .24850 .28992 .33133 .37275	.57298 .59864 .62648 .65607 .68708	1.0395 1.0558 1.0743 1.0947
1.0	.41416	.71924	1.1406
2.0	.82833	1.07580	1.4338
3.0	1.24250	1.46010	1.7793
4.0	1.65670	1.85490	2.1477
5.0	2.07080	2.25520	2.5285
6.0	2.48500	2.65870	2.9167
7.0	2.89920	3.06440	3.3100
8.0	3.31330	3.47150	3.7067
9.0	3.72750	3.87970	4.1061
10.0	4.14160	4.28870	4.5075

TABLE V. - ELECTRODE COORDINATES FOR
RECTILINEAR ION BEAM WITH CIRCULAR
CROSS SECTION NEAR BEAM EDGE

R	z/a							
	X = 0	X = 0.5	X = 1.0	X = 2.0				
1.00 1.25 1.50 1.75 2.00	0	0.593 .611 .649 .699	1.000 1.009 1.033 1.072 1.115	1.683 1.687 1.702 1.727 1.756				
2.25 2.50 2.75 3.00 3.25		.804 .852 .898 .932 .951	1.161 1.211 1.259 1.310 1.355	1.791 1.830 1.872 1.915 1.959				
3.50 3.75 4.00 4.25 4.50 4.75 5.00			1.400 1.441 1.482 1.512 1.540 1.551	2.007 2.052 2.099 2.146 2.189 2.237 2.278				

TABLE VI. - ELECTRODE COORDINATES FOR RECTILINEAR ION BEAM WITH CIRCULAR CROSS SECTION AWAY FROM BEAM EDGE

z/a	r/a	z/a	r/a	z/a	r/a	z/a	r/a
X = 0		Χ =	0.5	X =	1.0	Χ =	2.0
0.2728 .5456 .8184 1.0910 1.3640	0.962 1.924 2.886 3.848 4.810	0.659 .870 1.108 1.356 1.609	0.751 1.801 2.788 3.767 4.733	1.000 1.173 1.384 1.611 1.849	0 1.619 2.667 3.660 4.644	1.730 1.904 2.104 2.317	0.994 2.314 3.400 4.429
1.6368 1.9096 2.1824 2.4550 2.7280	5.772 6.734 7.697 8.659 9.621	1.873 2.131 2.393 2.660 2.929	5.705 6.666 7.633 8.599 9.561	2.102 2.347 2.599 2.857 3.120	5.625 6.590 7.564 8.536 9.505	2.541 2.777 3.010 3.251 3.504	5.429 6.425 7.409 8.391 9.371

TABLE VII. - INNER ELECTRODE COORDINATES

FOR HOLLOW CYLINDRICAL ION BEAM

z/b	r/b					
	X = 0	X = 0.5	X = 1.0	X = 2.0		
0 .1 .2 .3 .4	a <sub>1</sub> .00000 .57984 .50662 .40454 .29523	b1.00000 .94153 1.09360 1.10880 1.00150	c1.00000 1.52880 2.36070 3.03930 3.39730	d <sub>1</sub> .00000 4.03090 11.00100 22.83400 39.09300		
.5 .6 .7 .8	.19691 .12003 .06687 .03405 .01584	.81254 .59487 .39410 .23669 .12904	3.35290 2.94820 2.32260 1.64540 1.05100	57.09100 72.41500 80.67000 79.51700 69.72300		
1.2 1.4 1.6 1.8	.00093 .00009 0	.01181 .00150 .00013 .00001	.14981 .02501 .00284 .00022	24.12400 6.98090 1.33890 .17162		
0 1.0 2.0 3.0 4.0	.60653 .00674 0	.60653 .06393 0	.60653 .60653 .00001	.60653 .54598 .01480 0		

<sup>&</sup>lt;sup>a</sup>At beam edge z/b = 0 (see fig. 24(b)).

<sup>b</sup>At beam edge z/b = 0.5946 (see fig. 24(b)).

<sup>c</sup>At beam edge z/b = 1.000 (see fig. 24(b)).

<sup>d</sup>At beam edge z/b = 1.6818 (see fig. 24(b)).

00 00 00 00 00 8.9044553E-01 3.4963360E-01 5.0109286E-01 7.2206221E-01 .7840775E-01 8.3462061E-01 9.4564487E-01 .8079878E-01 .8985595E-01 2.2557276E-01 .6254488E-01 3.0425158E-01 4.4858510E-01 1.7076761E-01 .8511509E-01 .9793874E-0] 5.5504799E-0 6.1008136E-0 1.6557144E-0 1.6689474E-0 L.6852541E-0] .7358633E-0 .7694319E-0 .9498834E-0 6.658565E-0 1.6590387E-0 1.0000001E .2532106E .3875291E 1.42971846 .0533144E .1054160E .1561630E .2054491E .2994344E .3441679E 3-4 
 1

 0
 11 a V 7.2301837E-02 4.2971812E-01 2.9092681E-02 4.3575742E-02 5.7985585E-02 8.6506767E-02 .0058527E-01 .1452462E-01 .2831423E-01 .4194529E-01 .0750718E-01 .7548927E-01 4.2156789E-01 4.6269212E-01 5.5686167E-01 5.9603973E-01 6.1720467E-01 6.2131492E-01 5.9784291E-01 5.8280764E-01 5.6446637E-01 5.4301158E-01 4.6183891E-01 1.4559204E-02 .6841175E-01 ..2443286E-01 4.9890723E-01 5.3027326E-01 5.7875361E-01 6.0881998E-01 6.1725439E-01 5.1863534E-01 4.9152240E-01 6.2128334E-01 6.0938472E-01 SINCTRODE COORDINATES FOR CONTENDING CYLINCETOR FLOW (\*/\*\*) 00 00 00 9.4347788E-01 7.1046750E-01 8.8604332E-01 .1806747E-01 .29023136-01 .3514885E-01 .4164060E-01 .1657337E-01 3.6859320E-01 4.2266027E-01 5.3531178E-01 5.9318770E-01 6.516**7**089E-01 .6930026E-01 8.2790759E-01 1.0187791E-01 1.0343715E-01 1.0594428E-01 1.0929112E-01 .2331023E-01 1.7846812E-0 2.2076759E-0] •6709189E-01 4.7835662E-0 1.0134754E-0 .1336571E-0 ..0000001E .0554203E .1095738E .1623260E .2135783E .2632744E .3114092E .3580369E .40328135 1.4473448E 0.0 :1 1.5676782E-02 3.1308669E-02 4.6855480E-02 6.2284440E-02 7.7570459E-02 9.2694856E-02 .3697898E-01 .9457661E-01 4.8444563E-01 6.4172279E-01 × .0764398E-01 .2240783E-01 .5135194E-01 2.2012883£-01 .8361744E-01 .4176071E-01 4.4211587E-01 5.2164348E-01 5.5379397F-01 5.8098834E-01 **6.**0332389E-01 6.2090467E-01 6.3384263E-01 6.4225804E-01 6.4628109E-01 6.4605217E-01 6-2142304E-01 5.8680097E-01 5.6459342E-01 4.8061167E-01 4.4734451E-01 6.3345532E-0 6.0580840E-0] 5.1132942E-0 .. 3937621E-0 00 00 0 00 7.3193461E-03 .4815383E-02 2.2484176E-02 3.0321851E-02 .8324289E-02 4.6487704E-02 5.4808304E-02 6.3282333E-02 .1905963E-02 8.0675788E-02 .2741862E-01 .3767502E-01 .9545741E-01 .1471918E-01 6.3692459E-01 6.9843165E-01 .5985788E-01 8.2095520E-01 8.8148860E-01 9.4123783E-01 .2659134E-01 .8154937E-01 .7559668E-01 .5457456E-01 .7563984E-01 .0000001E .3722567E 1.4653514E .4194048E .0575935E .1138608E .1686749E .2219443E .3237042E .2736202E ı TABLE VIII. C П 1.4403409E-02 5.1229439E-02 6.7806510E-02 8.4135733E-02 1.0021819E-01 4.6535114E-01 1.7327307E-02 .1605496E-01 .3164710E-01 .4699567E-01 .6210168E-01 2.3402917E-01 3.0004260E-01 3.6026066E-01 4.1479772E-01 4.6376501E-01 5.0727155E-01 6.0611091E-01 6.2886524E-01 6.4671565E-01 6.6820469E-01 6.6699437E-01 5.8678002E-01 4.9982693E-01 5.4542555E-01 5.7833529E-01 6.5978537E-01 6.7165611E-01 6.4573593E-01 6.0978640E-01 5.3163729E-01 6.7211226E-0 6.5829513E-0 6.2950262E-0 5.6067187E-0 >

9.6358502E-01 5.1765506E-01 5.1774804E-01 5.1802705E-01 5.1997507E-01 5.2099238E-0] 5.2219181E-01 5.2513174E-01 5.2686889E-01 5.5352730E-0] 6.2067297E-0] 6.7913482E-0] 7.1137643E-0 7.4517286E-01 7.8020428E-0] 8.5276045E-01 8.8970881E-01 9.2673761E-0 5.1849155E-0 5.1914120E-0 5.2357213E-0 5.3814775E-0 5.7266129E-0 5.9517208E-0 6.4878311E-0 8.1616473E-0 .0000001E 1.0357440E 1.0705919E .1367877E .1677840E .1971918E .2249157E .2509091E 1.2751882E .1043358E × 0.6 11 1.6830868E-02 2.5234791E-02 6.6957579E-02 3.3624927E-02 5.0345736E-02 5.8667475E-02 7.5211752E-02 8.3425789E-02 8.4177403E-03 4.1996744E-02 ..6250279E-01 2.7518806E-01 .9927134E-01 .3372754E-01 .6560768E-01 3.2086524E-01 .4396825E-01 3.6393096E-01 3.8069745E-01 4.0453754E-01 4.1161261E-01 4.0034621E-01 .9470601E-01 1.9423615E-0] 4.1549208E-01 4.1622600E-01 4.1388389E-01 4.0855455E-01 3.8938621E-0] 3.7582074E-0] .5981377E-01 .4154598E-01 3.2121273E-0] 2.9902162E-01 .2375295E-0 > 00 8.2644712E-01 9.5718505E-01 4.1072260E-01 4.1110741E-01 4.1174780E-01 4.1264259E-01 4.1378975E-01 4.1518709E-01 4.1683171E-01 4.1872061E-01 4.2085011E-01 4.2321626E-01 4.3844246E-01 4.5887626E-01 4.8387180E-01 5.1279983E-01 5.4507865E-01 5.8018293E-01 6.1763994E-01 6.5702249E-01 6.9794099E-01 7.4003679E-01 7.8297635E-01 8.7015477E-01 9.1382142E-01 4.1059425E-01 1.0000001E 1.0420388E ..0830936E 1.1615464E 1.3320895E 1.1229811E .1986695E .2342733E .2683344E .3008966E × 0.4 11 3.0828995E-02 7.1604072E-02 2.0564585E-02 4.1072036E-02 5.1286758E-02 6.1466322E-02 8.1693500E-02 9.1728344E-02 1.9695296E-01 2.4067456E-01 2.8128519E-01 3.5226841E-01 3.8236013E-01 4.3138507E-01 4.5026961E-01 3.3208930E-01 1.0285877E-02 1.0170255E-01 1.5046891E-01 3.1853940E-01 4.6540889E-01 4.7683284E-01 4.8458929E-01 4.8874348E-01 4.8937808E-01 4.8659261E-0] 4.8050415E-01 4.7124676E-01 4.5897142E-01 4.4384486E-0] 4.2604782E-0] 4.0577304E-0 3.8322098E-0] 3.5859436E-0] 4.0874477E-0 × 00 00 00 00 800 9.4976479E-01 8.9880406E-01 .9564809E-01 .4734851E-01 PABLE VIII. - CONTINUED. 2.8144868E-01 2.6515514E-01 2.6536427E-01 2.6599005E-01 2.6702865E-0] 2.6847383E-01 2.7031718E-01 2.7254844E-01 2.7515606E-01 2.7812724E-01 2.8510652E-01 3.0796298E-01 3.3727531E-0] 4.1029850E-0 4.5220320E-0 4.9680501E-0 5.4357539E-0 .9205984E-0 6.4185706E-0 .9260486E-0 .4397113E-01 3.7172569E-0 .0000001E .0493007E ..3956122E .0974816E .1443867E .1898940E .2339228E .2764422E .3174812E .3571417E  $\bowtie$ 0.2 Н 3.9561192E-01 3.8413405E-02 5.1153300E-02 6.3838983E-02 7.6458250E-02 8.8999655E-02 ..1380736E-01 .2605502E-01 2.4121209E-01 2.9296916E-01 4.5642468E-01 × 1.2823116E-02 2.5632195E-02 1.0145261E-01 .8543078E-01 3.4046437E-01 4.2223080E-01 4.8616425E-01 5.1148127E-01 5.3242416E-01 5.6145254E-01 4.2562461E-01 3.8357151E-01 5.4905587E-01 5.6970347E-01 5.7391128E-01 5.7419226E-01 5.7067636E-01 5.6350801E-0] 4.7881162E-0 5.5284489E-0 5.3885795E-0 5.2172913E-0 5.0164882E-0 4.5340990E-0 ⊱

ELECTRODE COORDINATES FOR CONVERGING CYLINDRICAL FLOW  $(r/r_{
m O} < 1)$ 

TABLE VIII. - CONCLUDED. ELECTRODE COORDINATES FOR  $\mbox{CONVERGING CYLINDRICAL FLOW } (r/r_0 < 1)$ 

Y	X	Y	х
X =	0.8	Χ =	1.0
0. 6.9609271E-03 1.3918603E-02 2.0869779E-02 2.7811222E-02 3.4739711E-02 4.1652042E-02 4.8545030E-02 5.5415553E-02 6.2260466E-02 6.9076721E-02 1.0262334E-01 1.3501944E-01 1.6594096E-01 1.9510403E-01 2.2226539E-01 2.4722046E-01 2.6979982E-01 2.6979982E-01 2.8986560E-01 3.0730811E-01 3.2204290E-01 3.3400864E-01 3.4949506E-01 3.5299808E-01 3.5369632E-01 3.5163151E-01 3.4686594E-01 3.3948213E-01	0.8  6.0113725E-01 6.0120879E-01 6.0142340E-01 6.0142340E-01 6.028104E-01 6.0292333E-01 6.0370734E-01 6.0463250E-01 6.0569791E-01 6.0690294E-01 6.0824649E-01 6.1700452E-01 6.2903718E-01 6.4413850E-01 6.4413850E-01 6.6206996E-01 7.0537417E-01 7.3020023E-01 7.5677392E-01 7.5677392E-01 7.8482060E-01 8.1406850E-01 8.1406850E-01 8.7509794E-01 9.0635314E-01 9.3775697E-01 9.6905564E-01 1.0000001E 00 1.0303469E 00 1.0598599E 00 1.0883116E	X =  0. 5.7926631E-03 1.1582931E-02 1.7368407E-02 2.3146702E-02 2.8915439E-02 3.4672235E-02 4.0414739E-02 4.6140609E-02 5.1847492E-02 5.7533106E-02 8.5562512E-02 1.1272692E-01 1.3876833E-01 1.6345069E-01 1.8656168E-01 2.0791291E-01 2.2733941E-01 2.4469884E-01 2.5987023E-01 2.7275310E-01 2.8326694E-01 2.9135070E-01 2.9696273E-01 3.0008121E-01 3.0070402E-01 2.9884966E-01 2.9455707E-01 2.8788637E-01 2.7891851E-01	6.6808197E-01 6.6813859E-01 6.6830828E-01 6.6859109E-01 6.6859109E-01 6.6898677E-01 6.6949506E-01 6.7011576E-01 6.7084841E-01 6.7169255E-01 6.7264785E-01 6.7371358E-01 6.9028537E-01 7.0241039E-01 7.1689513E-01 7.3356234E-01 7.5221908E-01 7.7266063E-01 7.7266063E-01 7.7266063E-01 7.7266063E-01 8.1803695E-01 8.4252597E-01 8.6791050E-01 8.9395707E-01 9.2042912E-01 9.4708763E-01 9.7369186E-01 1.0000001E 00 1.0257705E 00 1.0507622E 00 1.0747361E 00
3.2958314E-01 3.1729210E-01 3.0275180E-01 2.8612359E-01 2.6758647E-01 2.4733526E-01 2.2557906E-01	1.1154850E 00 1.1411756E 00 1.1651936E 00 1.1873662E 00 1.2075390E 00 1.2255792E 00	2.6775547E-01 2.5451967E-01 2.3935304E-01 2.2241644E-01 2.0388784E-01 1.8396113E-01	1.0974551E 00 1.1186845E 00 1.1381906E 00 1.1557378E 00 1.1710823E 00 1.1839612E 00

00 6.0827674E-01 6.0123022E-01 5.0240499E-01 8.2451626E-02 -6.4813845E-02 6.1305435E-01 6.1300728E-01 6.1251867E-01 6.1228603E-01 6.1199106E-01 6.1162354E-01 5.8880171E-01 4.5149205E-01 3.8638656E-01 -2.4128343E-01 6.1308981E-0 6.1308096E-0 6.1293600E-0 6.1283527E-0 6.1269876E-0] 5.6930873E-01 5.4107837E-01 3.0490550E-01 2.0455766E-01 -7.0230833E-01 -4.5181609E-0 -1.0000008E .. 2801633E ..8886706E -4.5658393E -5.8030006E -1.3539232 .7755879E -3.6326426E  $\bowtie$ 0.4 II 00 00 00 00 00 00 2.8156436E-02 00 5.6329107E-02 8.4534138E-02 00 00 - ELECTRODE COORDINATES FOR DIVERGING CYLINDRICAL FLOW  $(r/r_{
m O}>1)$ × 1.1278749E-01 1.4110482E-01 1.6950149E-01 2.2659205E-01 4.3093650E-01 5.8280022E-01 7.4087051E-01 9.0604094E-01 ..9799242E-01 2.5531434E-01 2.8417275E-01 36470670. .4514924E 2.0863557E 1.2606677E 1.6522315E 1.8635987E 2.5694041E 4.0453506E 4.7776297E 2.3213259E 2.8315707E 3.1089087E 3.4026390E 3.7141906E 4.3985717E 5.1890756E 5.6457168E 6.1762113E 5.8593919E  $\succ$ 3.3632539E-01 -5.7638660E-02 3.3798319E-01 3.4121434E-01 3.4617814E-01 2.5095502E-01 1.9855171E-01 4.6601564E-02 3.3680530E-01 3.3704796E-01 3.3744437E-01 3.3942334E-01 3.4028590E-01 3.4218574E-01 -1.8452465E-01 -3.3756696E-01 3.3864893E-0 3.4317659E-01 3.4762563E-0] 3.4934852E-01 3.1820042E-01 2.9026981E-01 1.3115807E-01 -5.2095791E-01 -7.3973613E-0] -1.0000007E -1.3091990E 1.6765402E -2.1136354E -4.0264481E -2.6355836E -3.2630137E -4.9773338E -6.2246597E × 0.2 H 00 00 00 000 4.6690750E-02 ..0092498E-02 9.3560911E-02 00 00 00 00 00 00 00 00 2.3334026E-02 1.1711662E-01 1.6456644E-01 .8849541E-01 .3683830E-01 3.6109524E-01 9.2301402E-01 ..4077909E-01 .1258137E-01 4.9112276E-01 7.7152793E-01 × 6.2773326E-01 ..0826651E .2509553E .6154616E .8127676E ..4283786E .0209011E 2.2405012E 2.4722355E 2.7167856E 2.9748363E -2470645E 3.5341515F 3.8368448E 4.1561400E 4.4937255E 6.2265034E .6802182E 4.8530455E 5.2419587E  $\succ$ -7.4505806E-09 7.1382374E-03 .4091402E-02 2.0854697E-02 2.7424648E-02 3.3796206E-02 3.9965063E-02 4.5926630E-02 5.1676139E-02 5.7209179E-02 6.2520504E-02 8.5579171E-02 2.2770494E-02 00 .0231915E-01 .1387070E-01 9.0299398E-02 6.2681124E-02 -3.0996077E-02 1.1201806E-01 1.0697266E-01 -1.0044712E-01 -4.2648645E-01 -5.8458941E-01 -7.7403412E-01 -1.8773461E-0 -2.9540533E-01 -1.0000006E -1.2687183E -6.5149492E -1.5877137E .9661546E -2,4153753E -2.9497579E -3.5883874E -4.3585593E -5.3044917E TABLE IX. 0 II 7.1844539E-02 9.0445459E-02 00 00 8 00 00 00 00 00 1.757966E-02 3.5412857E-02 5.3500735E-02 ..4780346E-01 1.8735106E-01 00 00 00 8 00 00 1.0930475E-01 ..2842366E-01 1.6744551E-01 2.9088010E-01 5.1854261E-01 6.4309365E-01 7.7511073E-01 4.0121142E-01 9.1486998E-01 .0626813E .2188907E .7419094E .9358589E .3838814E .5580718E 2.1403832E 2.3559130E ..8213036E 1.0714571E 3-3330855E 2.5828076E 3.6057347E 3.8887087E 4.1812666E 4.4832159E 4.7965171E 5.1298906E 5.5149460E Н

000 00 2.5009155E-02 9.6429423E-01 7.9904696E-01 -2.95486**75**E-01 8.9020342E-01 6.8813410E-01 5.5433637E-01 2.0262799E-01 -6.1699C17E-01 3.9396785E-0 1.1667078E 1.1522043E 1.1063208E -1.0000010E -1.4583801E -2.0113251E -2.6873249E -3.5334548E -4.6429169E 1.1743571E 1.1720365E 1.1710039E 1.1697749E 1.1683443E 1.1648594E 1.1331048E 1.0703923E 1.0236664E 1.1739884E 1.1735258E 1.1728760E 1.1742649E × ت. 0 ELECTRODE COORDINATES FOR DIVERGING CYLINDRICAL FLOW  $({
m r}/{
m r_0}>1)$ II 8 00 00 00  $\times$ .5917358E-02 3.8172317E-01 7.7638677E-01 9.8219366E-01 3.7951939E-02 5.7668148E-01 1.1390967E-01 1.5194231E-01 .9002859E-01 3.4317285E-01 2.2818174E-0 3.0474097E-0] 2.6641490E-0 1.1953417E .4169867E 1.6482389E 1.8902038E 2.6921904E .9893748E 4.3778323E 6.2971761E 7.8122556E 2.1440212E .4109060E 3.3041949E 1.6387179E 3.9954974E 4.7902319E 5.2392960E 5.7355018E 6.9606043E > 4.4298564E-01 -9.4329997E-02 6.6813828E-01 5.6635293E-01 1.1713217E-01 -3.4575500E-01 8.1828870E-01 7.5127129E-01 -6.4453526E-01 9.9936248E-01 9.9402261E-01 9.9255724E-01 9.8236085E-01 9.6655575E-01 9.4382402E-01 9.1266372E-01 8.7142142E-01 2.9460378E-01 9.9993455E-01 9.9972075E-01 9.9739990E-01 9.9531379E-01 9.9885848E-0 9.9820534E-0 9.9643780E-0] 1.0000058E -1.0000009E -4.2834724E -1.4242450E -1.9335490E -2.5511064E -3.3129490E -5.6111254E × 0.67828 000 00 00 00 00 00 00 8 8 00 00 00 90 6.9831797E-02 5.3117205E-01 3.4908992E-02 1.0478216E-01 1.3977382E-01 1.7482034E-01 2.4513177E-01 3.1582220E-01 3.5134164E-01 7.1576786E-01 9.0642015E-01 2.0993522E-01 2.8042310E-01 H  $\times$ 1.1042771E 4.8491306E 7.9866989E 1.3103836E 1.5257256E 1.7512717E 1.9880102E 2.2369844E 2.4993252E 2.7762878E 3.0692970E 3.3800088E 3.7104117E 4.0629897E 4.4410203E 5.2944126E 5.7888023E 6.3547701E 7.0414249E  $\succ$ 00 00 00 8 8.8975743E-01 8.8930384E-01 8.8838217E-01 8.8696369E-01 8.8605536E-01 8.8500668E-01 8.7531930E-01 7.7607423E-01 6.4101368E-02 -1.3724078E-01 -3.7679445E-01 -6.6149026E-01 8.8958788E-01 8.8890299E-01 8.8773733E-01 8.8380989E-01 8.6176167E-01 8.4174818E-01 8.1373854E-01 7.2697217E-01 5.8646935E-01 4.9047390E-01 2.3286609E-01 6.6448924E-01 3.7369794E-01 -1.0000009E .8864979E -3.1835391E -4.0799958E -5.2666563E -7.0972426E -1.4034344E -2.4696444E × 9.0 H PABLE 00 8 00 8 00 × 6.5985871E-02 9.9014231E-02 .6521205E-01 2.9855577E-01 5.0249035E-01 6.7762592E-01 8.5882140E-01 3.2985843E-02 2.3169004E-01 3.3216655E-01 1.3208498E-01 1.9840921E-01 2.6506783E-01 2.9235959E 3.8691927E 5.0275726E 5.4847822E .3900613E .0471626E .4491020E .6644896E .1286179E .6438909E 3.2198635E 3.5343781E 4.2269456E 4.6112645E 5.9992197E 6.6050682E 8.7077599E .2436208E .8906810E .3793153E >

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00 00 00 00 00 00 00 00 00 00 00 00 8.4684141E-01 3.5091260E-01 2.5215045E-01 -1.0000020E .8965613E -1.9599242E 2.5222769E 2.3486246E 2.1419291E 1.6054527E ..2595371E 3.1270568E 3.1127447E 2.9660491E 2.8865396E 2.7878418E 3.1331460E 3.1311191E 3.1293434E 3.1242570E 3.1209409E 3.1171048E 3.1078557E 3.0284154E 3.1333990E 3.1323860E 3.0752689E 2.6674413E × 0.0 7 FOR DIVERGING CYLINDRICAL FLOW  $({
m r/r_o}>$ П 00 00 .2432590E-01 3.6107073E-01 5.7862142E-01 6.5139486E-01 7.2144340E-02 1.4430612E-01 2.8875186E-01 2.1650280E-01 4.3347694E-01 5.0598798E-01 .0919652E 5.8925108E 9.6113002E 2.2438950E 2.6522758E .5222776E 3.9907363E 5.0169928E 5.5874133E 6.2080304E 7.6614143E 1.0971956E .4662235E .8493993E 3.0773492E 4.4871411E 8.5479789E  $\succ$ 00 00 000 000 00 00 000 00 00 .6934704E-01 -4.2727039E-01 4.3901993E-01 4.5198262E-02 -1.0000015E -2.6036464E -1.7062655E .7835213E ..6447964E .4789948E .2816660E .0473700E -3.8139954E 2.2609916E 2.2602280E 2.2592726E 2.2540934E 2.2453883E 2.2416853E 2.2169207E 2.1810791E 2.1330031E 2.0712122E 1.9938900E 1.8988577E 2.2608008E 2.2579330E 2.2562073E 2,2515879E 2.2486878E × ੂ ਹ ELECTRODE COORDINATES 11 00 00 00 00 00 00 00 00 00 5.6917496E-02 1.7081126E-01 5.1401907E-01 5.7159666E-01 1.1384969E-01 2.2781690E-01 2.8488127E-01 3.4201905E-01 3.9924485E-01 4.5657336E-01 8.6197140E-01  $\times$ 1.1578182E 2.7835219E 1.4609435E 1.7731655E 2.0963447E 3.1519463E 3.5403725E 4.8612435E 5.3704993E 6.5463442E 1.0501963E 2.4324308E 3.9519627E 4.3906007E 5.9276203E 7.2485798E 8.0726312E 9.0947183E × 00 00 00 00 00 00 00 00 00 00 .4679531E-01 5.6613253E-01 9.5867082E-02 -2.0745360E-01 -5.6848438E-01 8.9816294E-01 3.5119139E-01 CONCLUDED. -1.0000011E ..2146531E 1.0243673E -2.9404981E .4693931E 1.4690239E 1.4664284E .4569779E .4164550E ..1288795E -3.9596832E 1.4695159E .4684080E .4675435F .4634347E 1.4615491E .4593985E 1.4406139E .3833315E .3398136E 1.2842290E -1.5195364E -2.1526857E -5.4016352E .4650601E  $\bowtie$ ı TABLE IX. o, B 00 00 00 00 00 00 00 4.3103422E-02 00 00 8.6220226E-02  $\times$ 1.2936380E-01 2.1578455E-01 4.3323155E-01 6.5396060E-01 8.7951779E-01 1.7254747E-0] 2.5908829E-01 3.4594821E-01 3.8953051E-01 3.0247179E-0 2.4125475E 4.9322571E 8.1316562E 9.4393312E 1.1113659E 1.3508922E .8583150E 3.0255391E 3.3585833E 5.4096707E 6.5371969E 7.2420303E 1.5994346E 2.1288799E 3.7123697E 4.0898345E 4.4947588E 2.7108584E 5.9383136E >

1.4286 1.4358 1.4421 1.4475 1.4585 95483  $\alpha$ ं 50.000 51.146 52.292 53.433 55.157 ħ Φ  $\approx$ 1.4286 1.4445 1.4594 1.4799 1.5142 1.5281 1.5400 1.5497 2549 Œ, о О 40.000 41.146 42.232 44.011 45.730 47.448 49.167 50.586 52.605 56.043 57.762 59.481 H 0 1.7696 1.7712 1.7719 1.6293 1.6456 1.6610 1.6752 .4286 .4563 .4825 .4825 .5306 .5527 .5735 .5932 .6118 1.7008 1.7120 1.7223 1.7316 1.7399 1.7473 1.7537 1.7591 1.7636 1.7671 0.62956 pr; 51.772 52.918 54.064 55.210 56.356 30.000 30.573 31.146 32.292 33.438 40.313 41.459 42.605 43.751 44.897 46.043 47.189 48.335 49.481 50.626 34.584 35.730 36.875 38.021 39.167 11 S >=; 1.8963 1.9175 1.9376 1.9565 1.9912 2.0068 2.0215 2.0350 2.0590 2.0693 2.0787 2.0869 45296 1.4527 1.5365 1.5365 1.5785 1.6153 1.6500 1.8630 1.7443 1.7728 1.7999 1.8258 1.8505 2.1003 2.1055 2.1126 2.1126 2.1146 39685  $\alpha$ 53.805 54.950 55.096 57.242 59.356 59.556 20.000 20.373 21.719 22.868 24.011 25.157 26.303 27.448 28.594 29.740 30.886 32.032 33.178 34.324 35.470 36.616 37.762 36.908 40.054 41.193 48.075 48.221 50.367 51.513 52.659 42.348 43.431 44.637 45.783 46.928 ं 11 Ø 3643 4069 4323 4706 5772 5900 6015 6119 6211 .6290 .6358 .6414 .6458  $\alpha$ વા વા વા વા વા  $\alpha$ ai ai ai ai ai anaaaa ai ai 35.783 36.929 38.075 59.221 40.367 41.313 42.859 44.856 44.950 47.242 48.388 49.534 50.680 51.626 52.972 54.118 55.264 56.410 57.555 0.16494 Ø 1.4286 1.4758 1.5508 1.6141 7244 7744 7744 1 8621 9118 9541 9949 0343 0723 1445 1787 2117 2434 2740 3033 3315 3585 П  $\alpha$ d FIFTOROLO  $\alpha \alpha \alpha \alpha \alpha \alpha$  $\alpha \alpha \alpha$ 10.000 10.873 11.719 12.865 15.137 16.303 17.448 18.594 19.740 20.686 22.032 23.178 24.324 25.470 26.616 27.762 28.908 30.054 31.199 32.345 33.491 34.637 Ø 2556 7774 8126 8464 8730 9403 9689 9963 0223 0703 0923 1128 1322 1501 1666 1818 1956 2080 2190 2286 2368 2436 2436 2490 2530  $\alpha$ : <u>ાં તાં તાં તાં</u> имими, 200000 иииии 200 52.712 53.858 55.004 56.150 41.253 42.369 43.545 44.691 45.837 46.983 46.128 49.274 50.420 51.566 58.442 59.588 29.794 30.940 32.086 53.232 34.377 θ 0 J! 4510 4562 5400 5827 6242 6643 7033 7410 1.4286 1.4629 1.4967 1.5302 1.6284 1.6921 1.7544 1.8154 9335 9907 0467 1014 1550 2073 2585 3084 3572 4047  $\alpha$ 44000 તાં તાં તાં તાં ાં વાં વાં વાં 0 .57296 1.14590 1.71890 2.29180 3.43770 4.58370 5.72960 6.87550 8.02140 9.16730 10.31300 11.45900 12.60500 13.75100 89700 .04300 .16900 .33500 62600 77200 91800 06400 21000 35600 50200 64800 Φ 

TABLE X. - OUTER ELECTRODE COORDINATES FOR CIRCULAR FLOW ION BEAM

2,0408 18.475 19.513 19.983 20.752 21.311 22.224 22.886 23.967 24.750 34.851 36.459 39.176 41.254 46.981 56.000 15.000 15.004 15.028 15.120 15.120 15.534 15.878 16.330 16.903 17.612 26.954 228.466 29.564 31.364 32.678 H  $\succ$ 1,2856 17.179 17.462 17.935 18.287 15.000 14.999 14.995 14.988 15.005 15.051 15.136 15.270 15.740 16.104 16.279 16.577 16.801 23.078 23.826 25.043 25.920 27.338 28.356 19.304 20.021 20.547 21.413 11 1.0 15.000 14.997 14.983 14.937 14.803 14.734 14.678 14.645 14.645 14.695 14.803 14.867 14.987 15.265 15.407 15.658 15.853 16.192 16.451 16.894 17.230 17.797 18.221 18.930 19.453 20.316 20.945 21.970 22.709 23.900 11  $\times$ 95483 14.962 15.082 15.298 15.469 15.000 14.997 14.981 14.929 14.856 14.529 14.597 14.643 14.736 14.815 16.000 16.400 16.706 17.226 18.277 18.766 19.576 20.169 21.138 21.837 22.968 4.771 4.684 4.606 4.546 4.517 ं H  $\times$ 82549 15.000 14.996 14.975 14.806 14.679 14.541 14.398 14.263 14.056 14.008 14.003 14.015 14.705 14.982 15.201 15.588 16.402 16.793 17.454 17.945 17.945 118.758 119.352 20.318 14.094 14.151 14.266 14.365 14.552 ं It Œ  $\sim$ 0,62996 15.000 14.994 14.966 14.872 14.541 14.324 14.085 13.835 13.582 13.339 13.115 13.034 12.923 12.859 12.779 12.698 12.689 12.689 12.736 12.822 12.908 13.087 13.242 13.536 13.776 14.208 14.546 15.131 15.372 16.310 II  $\times$ 0.39685 15.000 14.993 14.956 14.831 14.375 14.065 13.711 13.324 12.911 12.482 12.047 11.874 11.616 11.447 11.200 11.041 10.813 10.670 10.355 10.203 10.024 10.034 10.009 10.052 10.185 10.325 10.621 10.878 11  $\times$ 0.16494 15.0000 14.9910 14.9460 14.7900 14.5410 14.2110 13.8070 13.3390 12.8150 12.2420 11.6280 10.9800 10.7130 10.3060 9.6135 9.3331 8.9108 8.6292 8.2087 7.9311 7.5213 7.2548 6.8692 6.6251 6.2858 6.0837 5.8311 5.7081 5.5081 5.6381 5.8124 Ħ  $\times$ 8.47260 8.10270 7.53590 7.15020 6.56040 6.15990 5.54860 5.13420 4.50240 3.42350 2.98300 2.31290 1.86010 1.17160 15.00000 14.99000 14.93800 14.76000 14.47600 11.01800 10.21700 9.88320 9.36760 14.09400 13.62400 13.07400 12.45200 11.76500 0 lt .85 .90 .90 .90 .90 .90 90.05 .35 .35 .40 250 50 50 50 50 50 50 650.00 .75 .77 .80 .82  $\alpha$ 

TABLE XI. - INNER ELECTRODE COORDINATES FOR CIRCULAR FLOW ION BEAM

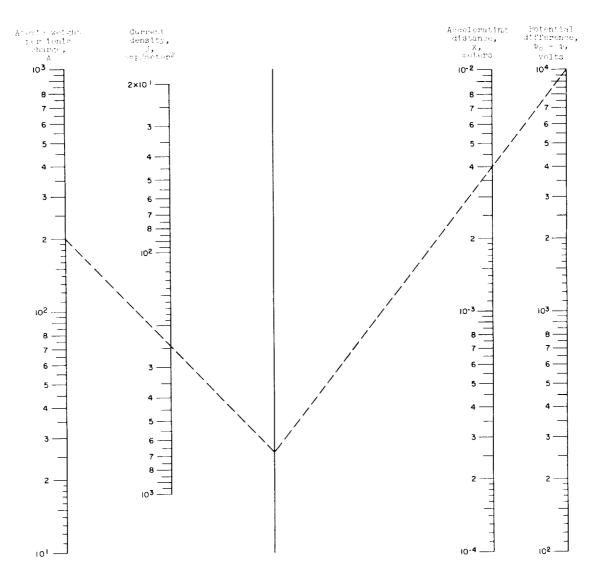


Figure 1. - Space-charge-limited flow between infinite plane electrodes.  $f=5.407\times10^{-8}A^{-1/2}(\phi_{\rm G}-\phi)^{3/2}x^{-2}$ . (See appendix 6 for rescaling.)

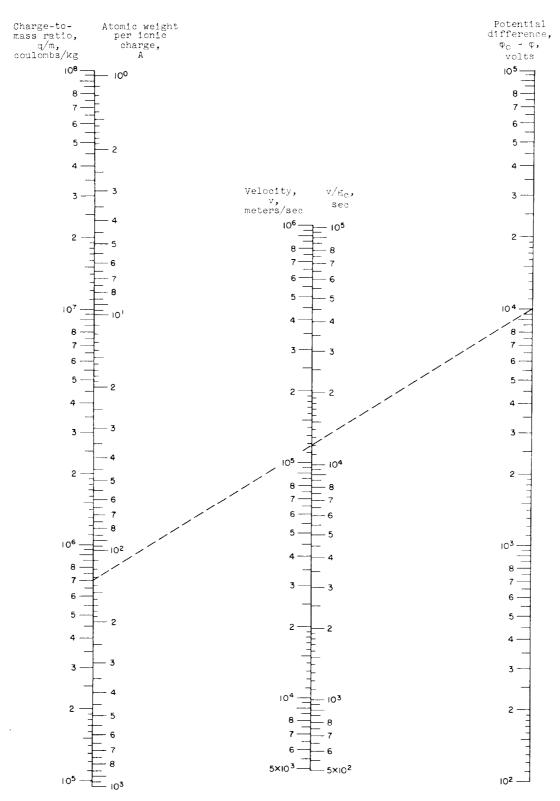
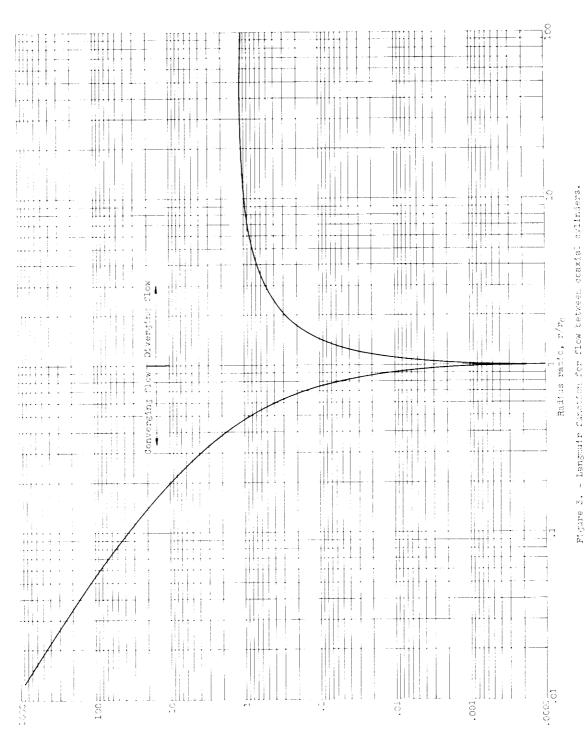


Figure 2. - Nomographic solution of  $\frac{1}{2}\;mv^2=q(\phi_0^{}-\phi_0^{}).$  (See appendix C for rescaling.)



Langraulr function, p2

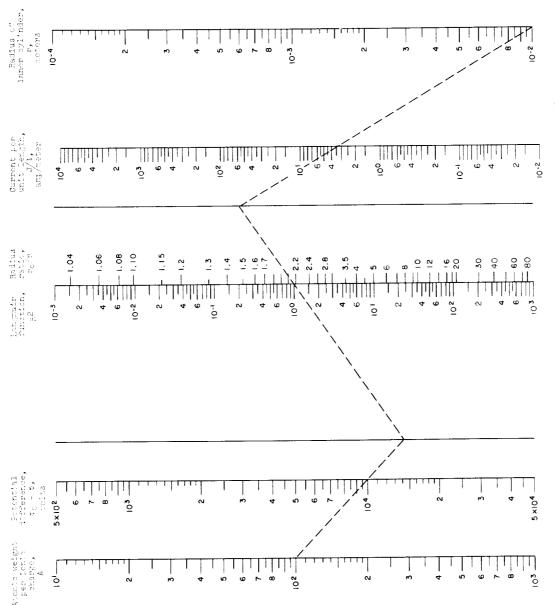


Figure 4. - Converging flow between coaxial sylinders. J/l =  $3.43 \times 10^{-7} k^{-1}/2 (\epsilon_{\rm G} - \phi)^{3/2} (\pi 62)^{-1}$  for  $z < r_{\rm G}$  note that  $z = (3.4)/2\pi r$ . (See appendix 0 for rescaling.)

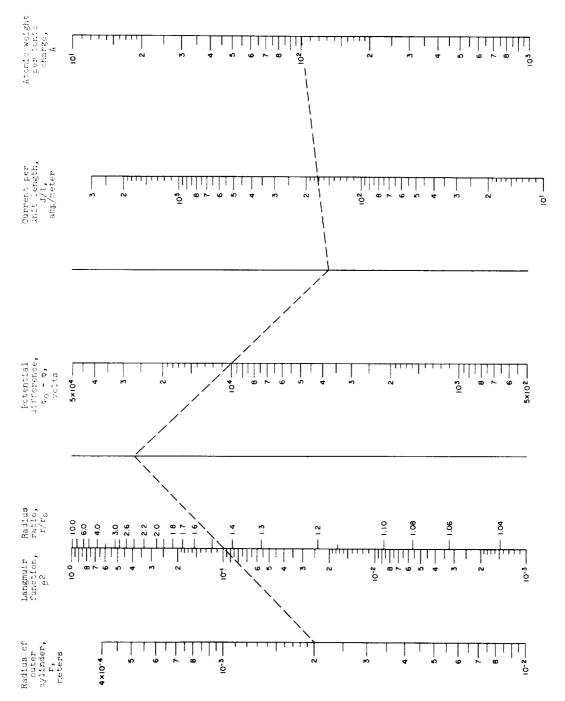
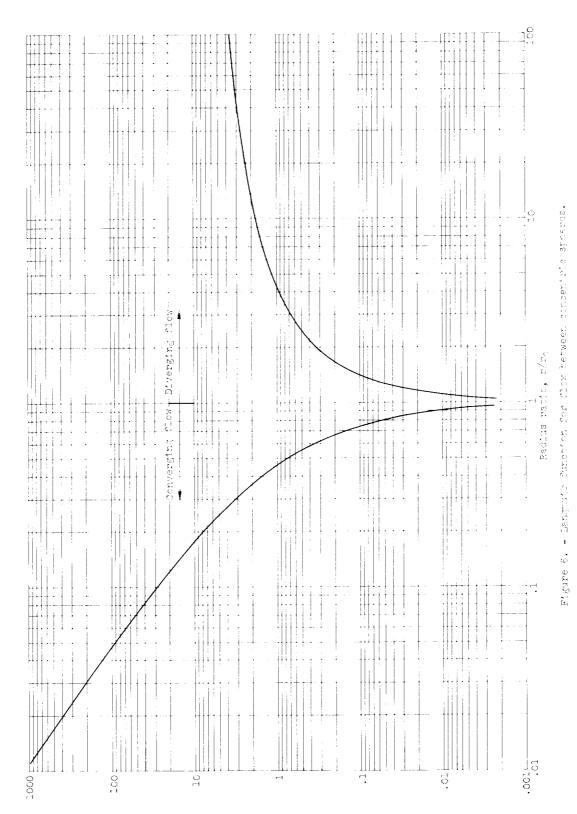


Figure 5. - Diverging flow between coaxial sylinders. J/l =  $3.43 \times 10^{-7} A^{-1}/2 (\phi_0 - \phi)^{3/2} (r p 2)^{-1}$  for r > r<sub>0</sub>; note that  $(3/1)/2\pi r$ . (See appendix C for rescaling.)



rengmutr function, a

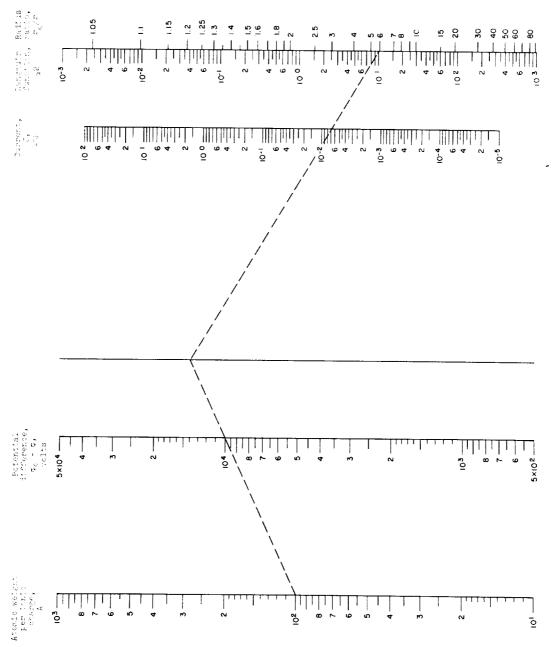


Figure 7. - Converging flow between concerned spinches.  $\vec{v} = \vec{v} \cdot \vec{v} + \vec{v} \cdot$ 

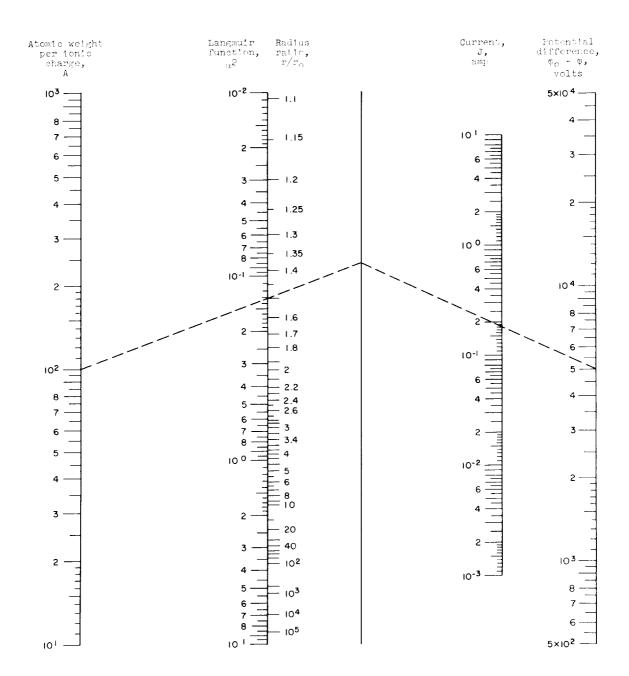


Figure 8. - Diverging flow between concentric spheres.  $J=6.87\times10^{-7}A^{-1/2}(\phi_0-\phi)^{3/2}a^{-2}$  for  $r>r_0$ ; note that  $J=J/4\pi r^2$ . (See appendix C for rescaling.)

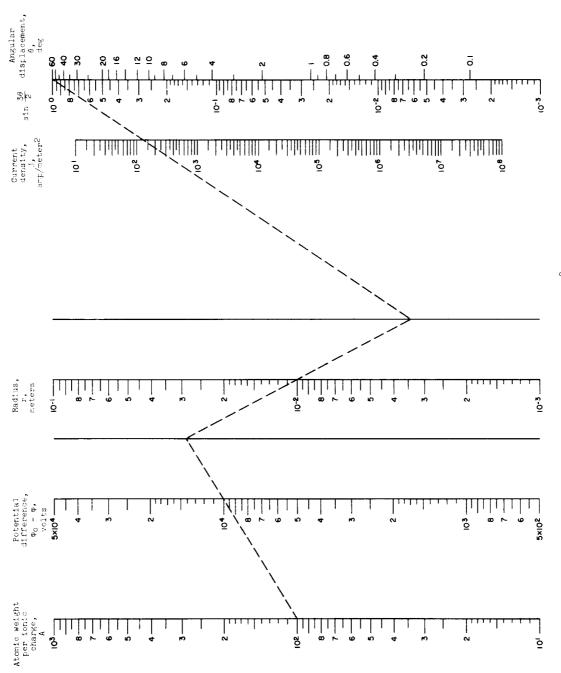


Figure 9. - Circular flow.  $\beta = 1.23 \times 10^{-7} \text{A}^{-1}/2 (\phi_0 - \phi)^{3/2} \left( \text{r sin} \frac{3\theta}{7} \right)^{-2}$ . (See appendix C for rescaling.)

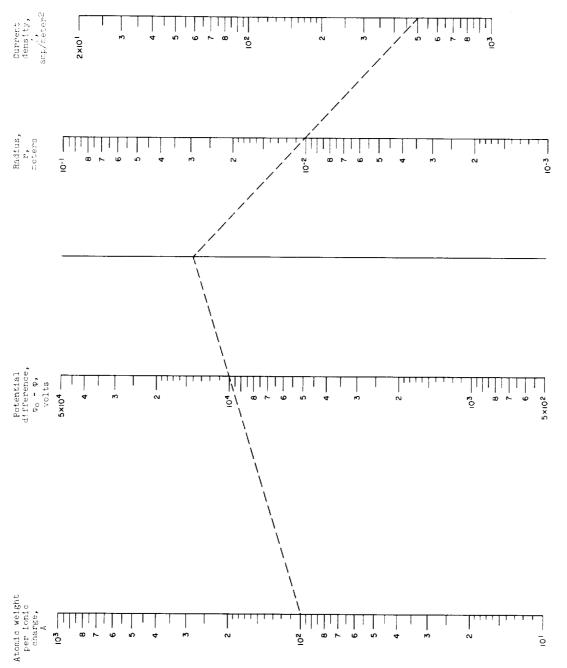


Figure 10. - Hypercelle flow.  $(=4.82 \times 10^{-7} \text{A}^{-1})^2 (\tau_0 = e)^{3/2} r^{-2}$ . (See appendix 0 for rescaling.)

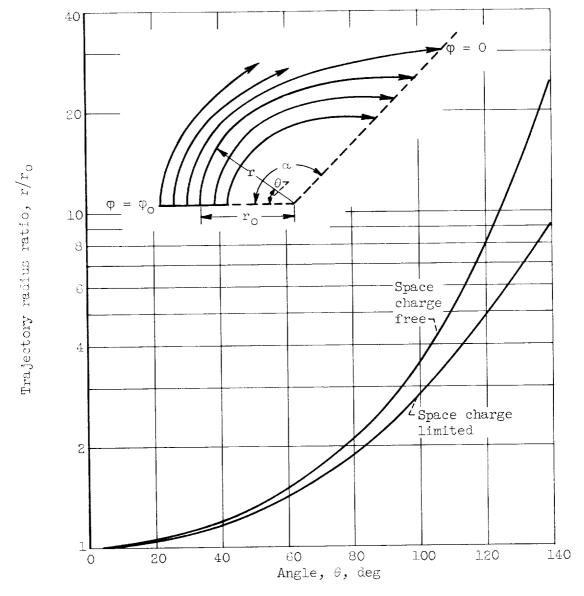
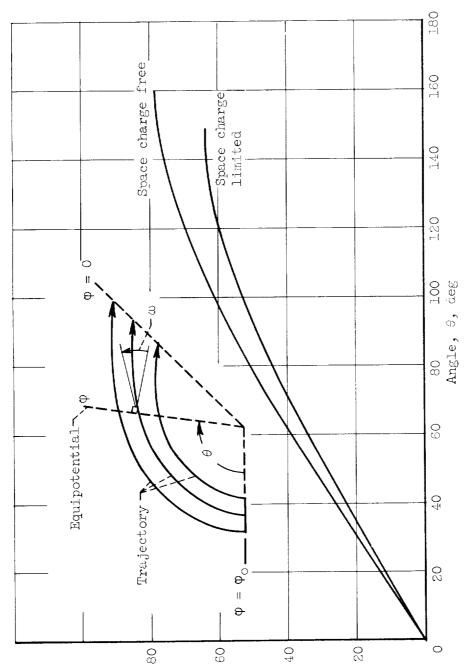


Figure 11. - General trajectory plot for flow between inclined planes (eqs. (41) and (48)).

Figure 12. - Angle between trajectories and normals to equipotentials for inclined planes (eqs. (42) and (49)).



Angle between trajectories and normals to equipotentials, w, deg

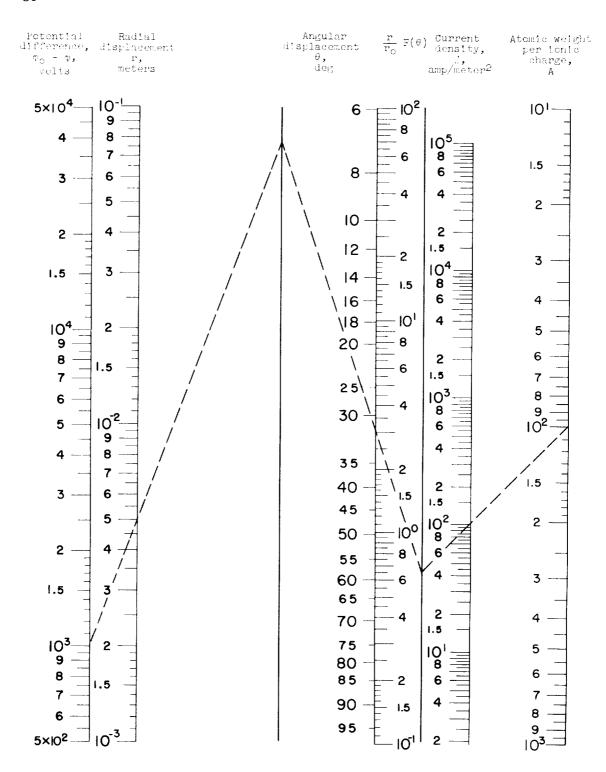


Figure 13. - Space-charge-limited flow between inclined planes.  $\beta = 5.467 \times 10^{-8} A^{-1/2} (\phi_0 - \phi)^{3/2} r^{-2} \left[ \frac{r}{r_0} F(\theta) \right].$  (See appendix C for rescaling.)

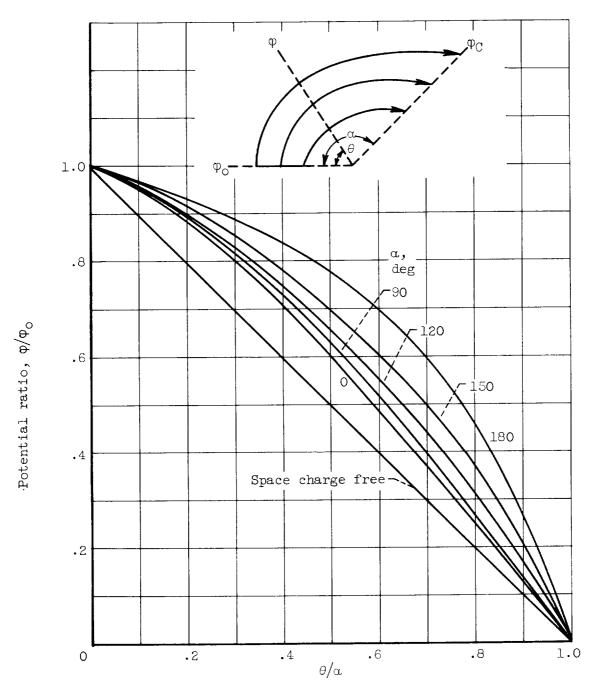


Figure 14. - Potential distribution between inclined plane electrodes (space-charge limited).

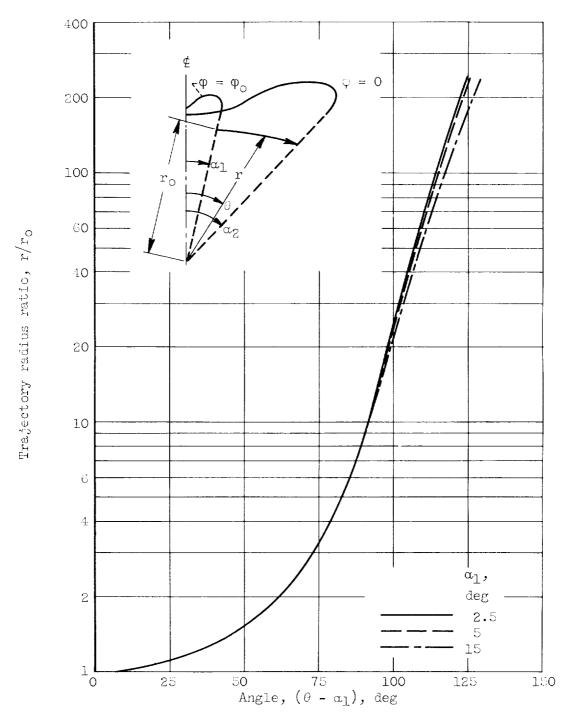
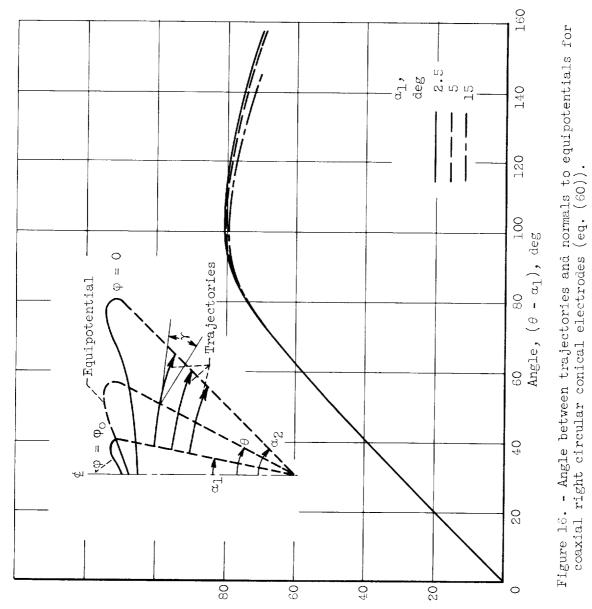


Figure 15. - General trajectory plot for flow between co-axial right circular cones (eq. (59)).



Angle between trajectories and normals to equipotentials, Y, deg

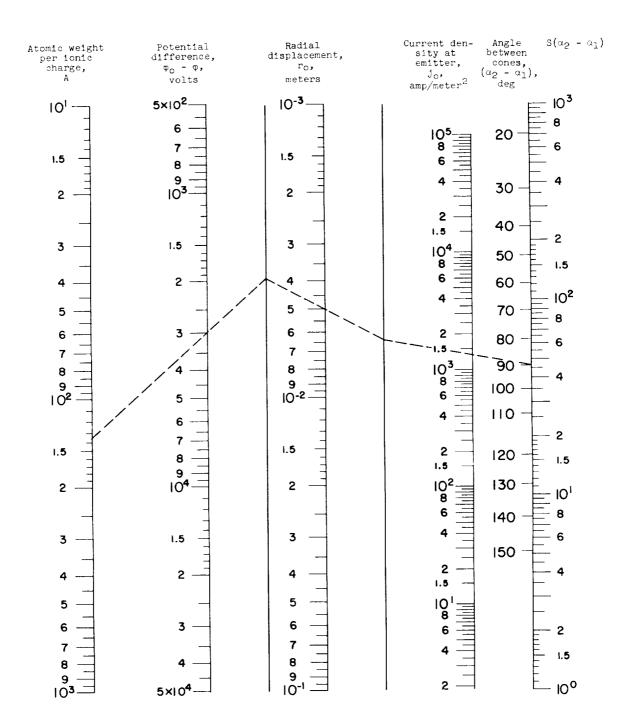


Figure 17. - Space-charge-limited flow between coaxial cones.  $j_{o} = 5.467 \times 10^{-8} \, \text{A}^{-1/2} (\phi_{o} - \phi)^{3/2} r_{o}^{-2} \text{S} (\alpha_{2} - \alpha_{1}) \, .$  (See appendix C for rescaling.)

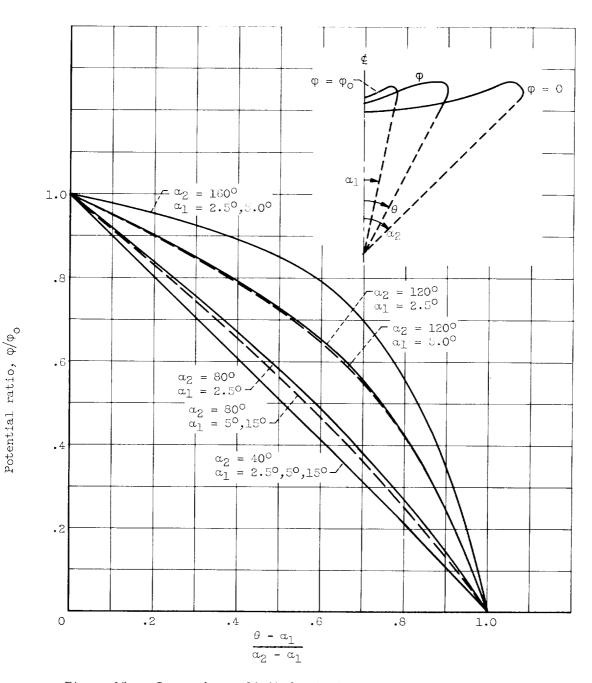


Figure 18. - Space-charge-limited potential distribution between coaxial cones.

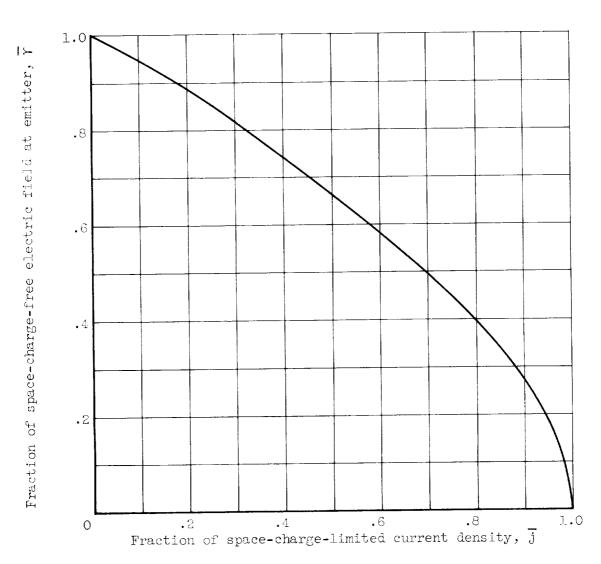


Figure 19. - Current density as a function of electric field at emitter (ref. 15).

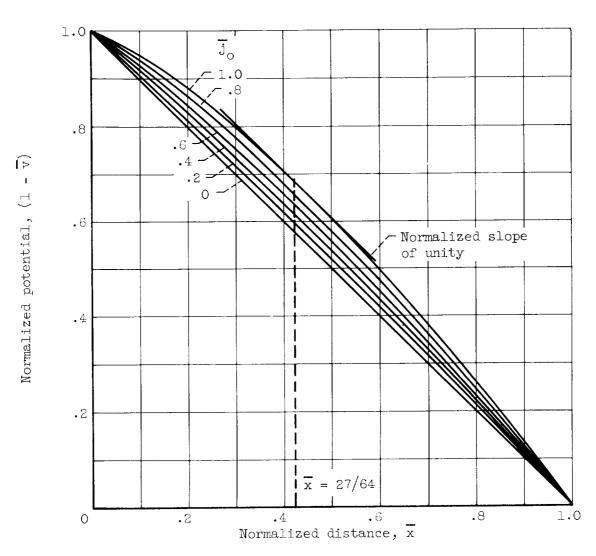


Figure 20. - Normalized potential distribution for partial space-charge flow (ref. 15).

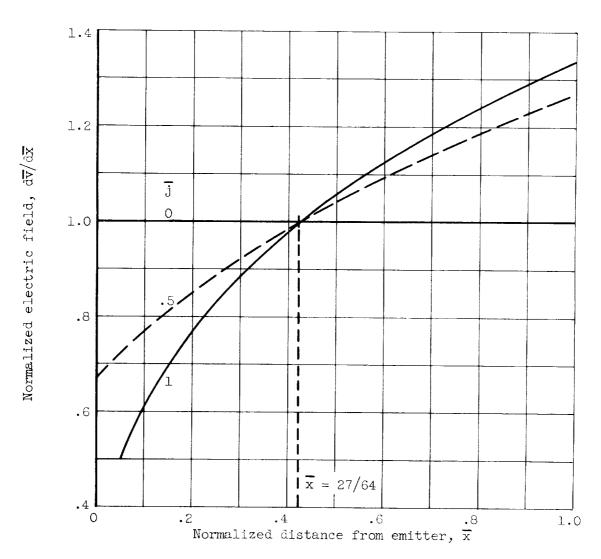


Figure 21. - Electric field in space between emitter and collector for several current densities (ref. 15).

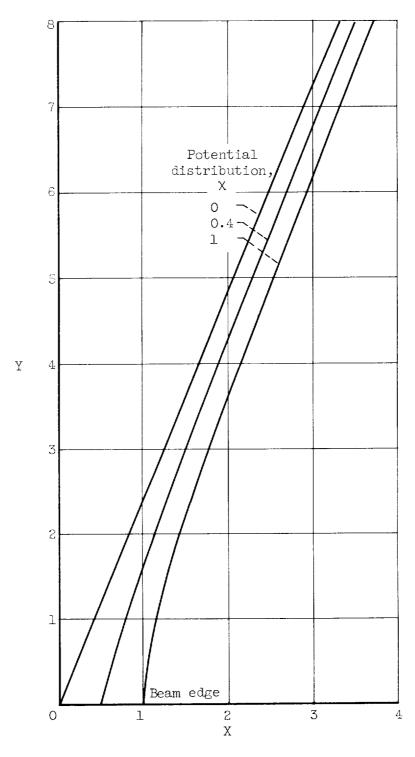


Figure 22. - Typical electrode shapes for a rectilinear slab ion beam.

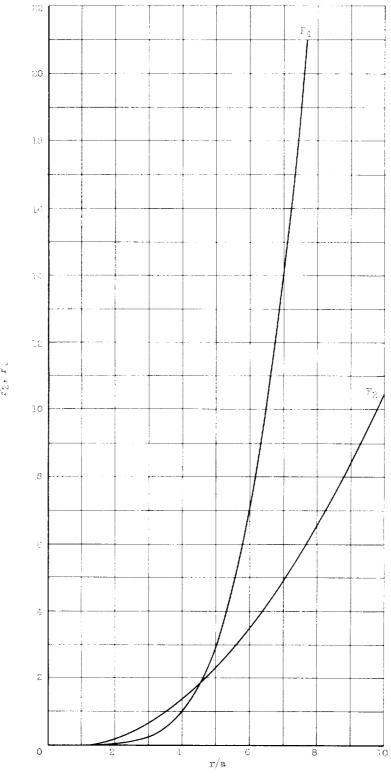
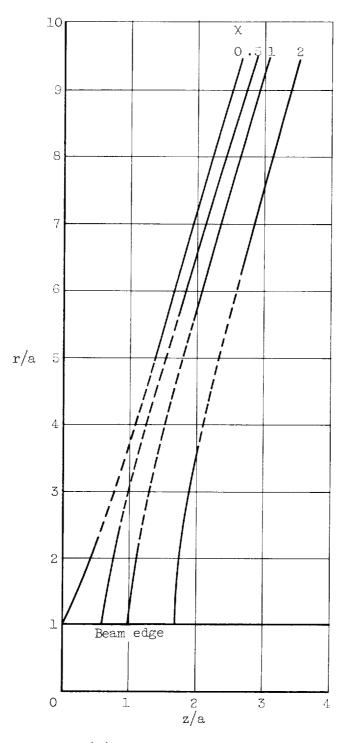


Figure 23. - Dominant terms in series expansion of potential function near edge of a rectilinear ion beam with circular cross section (eq. (79)).



(a) Outer electrode shapes.

Figure 24. - Typical electrode shapes for a rectilinear ion beam with circular cross section.

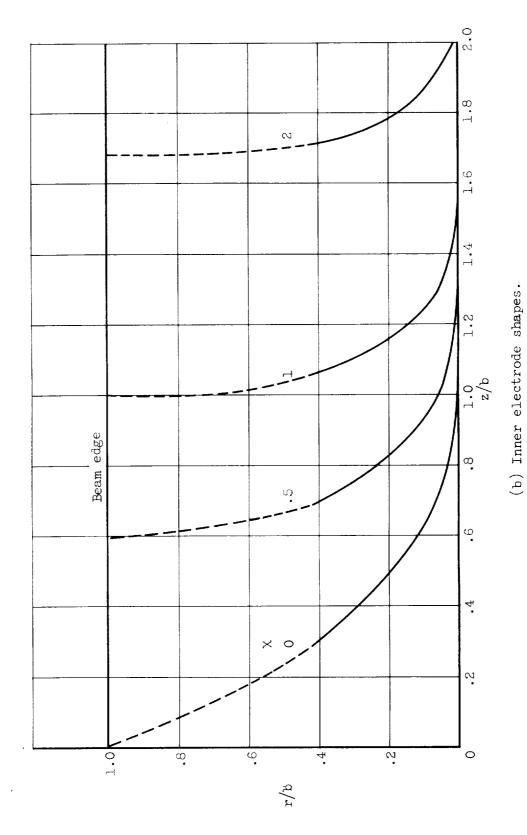


Figure 24. - Concluded. Typical electrode shapes for a rectilinear ion beam with circular cross section.

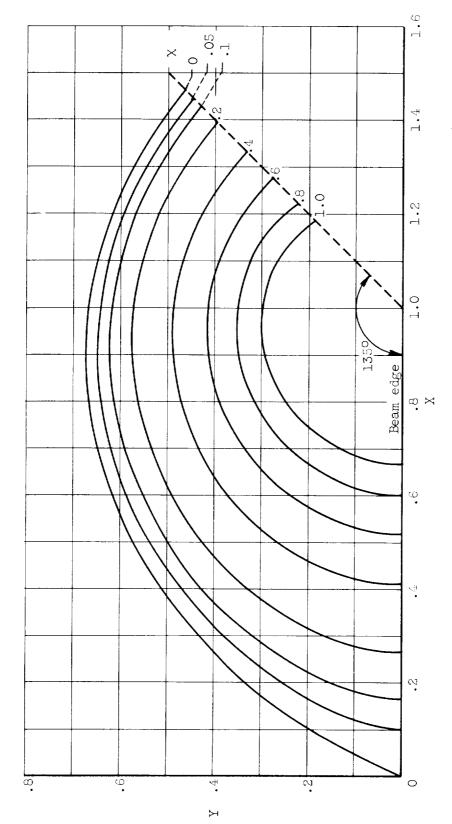
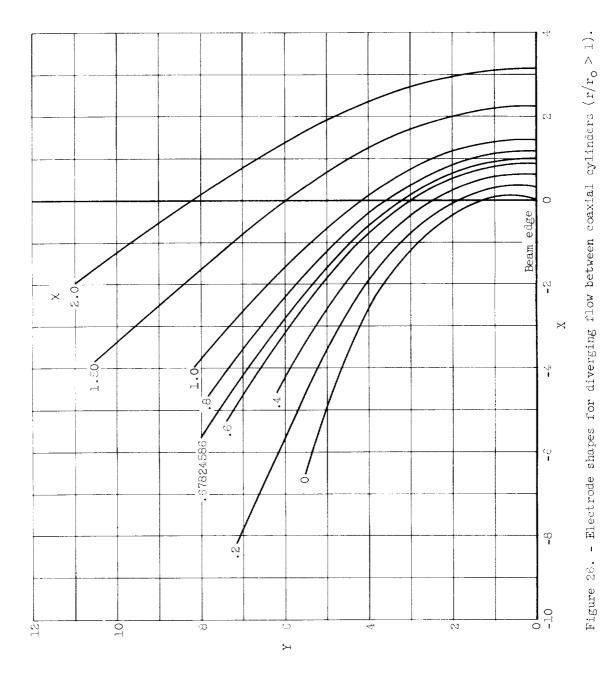
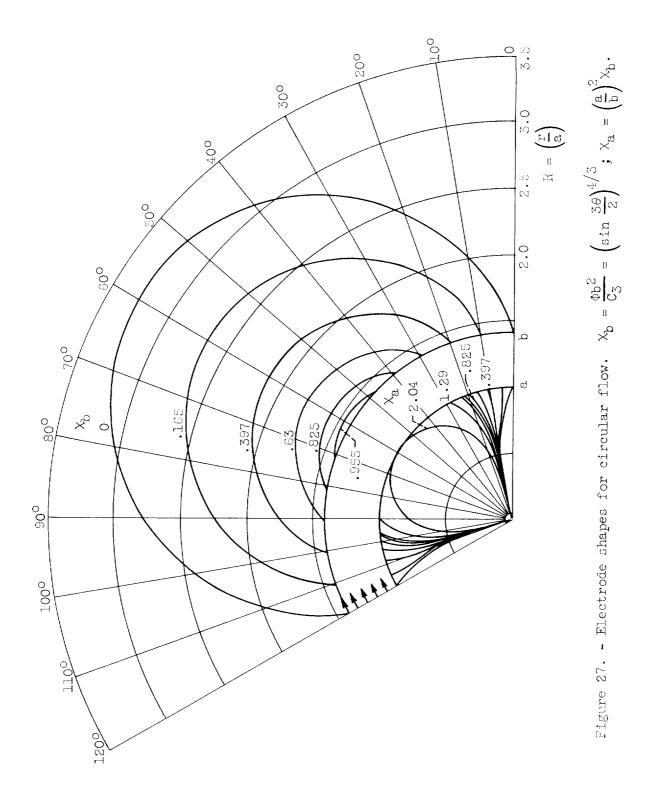


Figure 25. - Electrode shapes for converging cylindrical flow  $(r/r_{\rm O} < 1)$ .





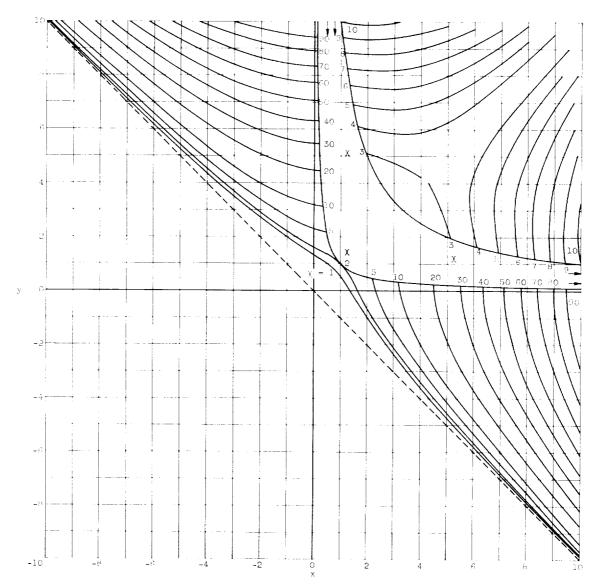


Figure 28. - Electrode shapes for hyperbolic flow.

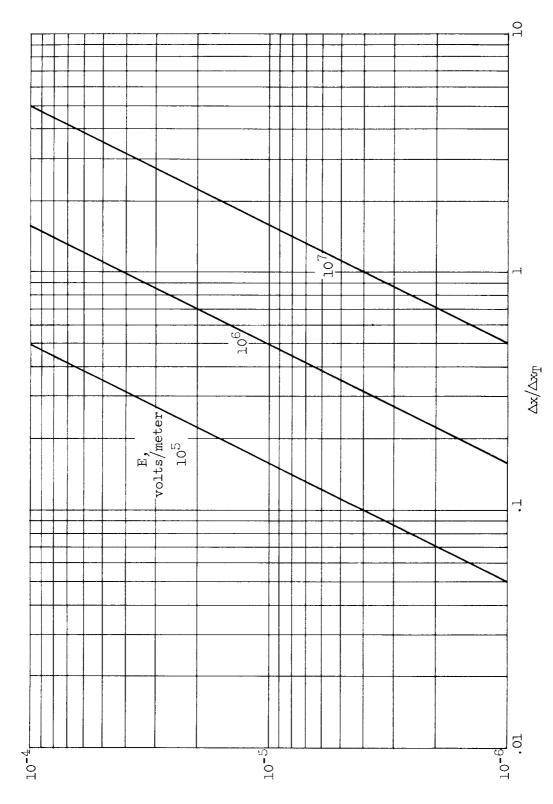


Figure 29. - Approximate ratio of ion beam spreading due to a surface irregularity to thermal spreading.

Hump radius, 1, meters

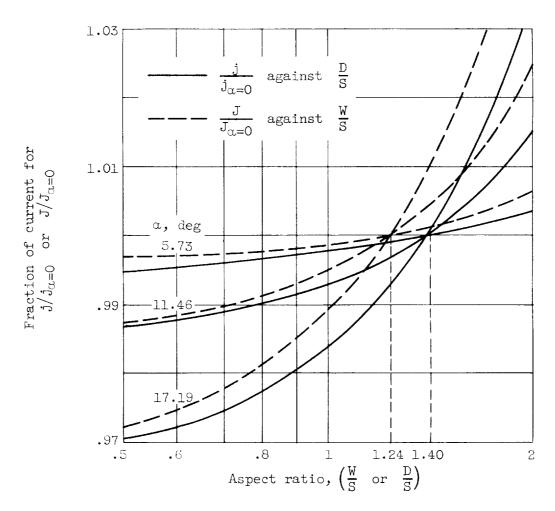
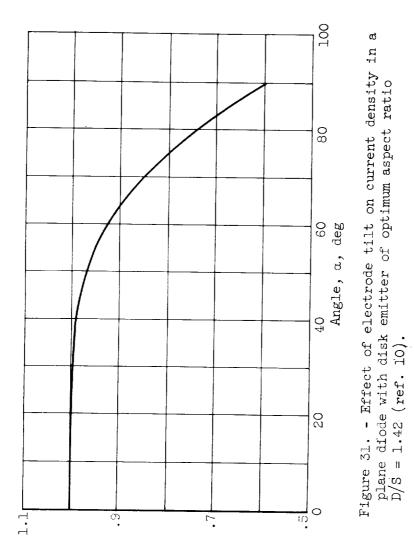


Figure 30. - Effect of electrode tilt on current density in a plane diode (ref. 10). (Rectangular emitter tilted about axis parallel to side and disk emitter.)



Fraction of total current for  $\sqrt{3}\omega = 0$ 

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